



- Outgrow your limits -

高性能計算基盤

- High Performance Computing Platforms-
#8

Analog Computing Implementations in Machine Learning

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2020/06/25

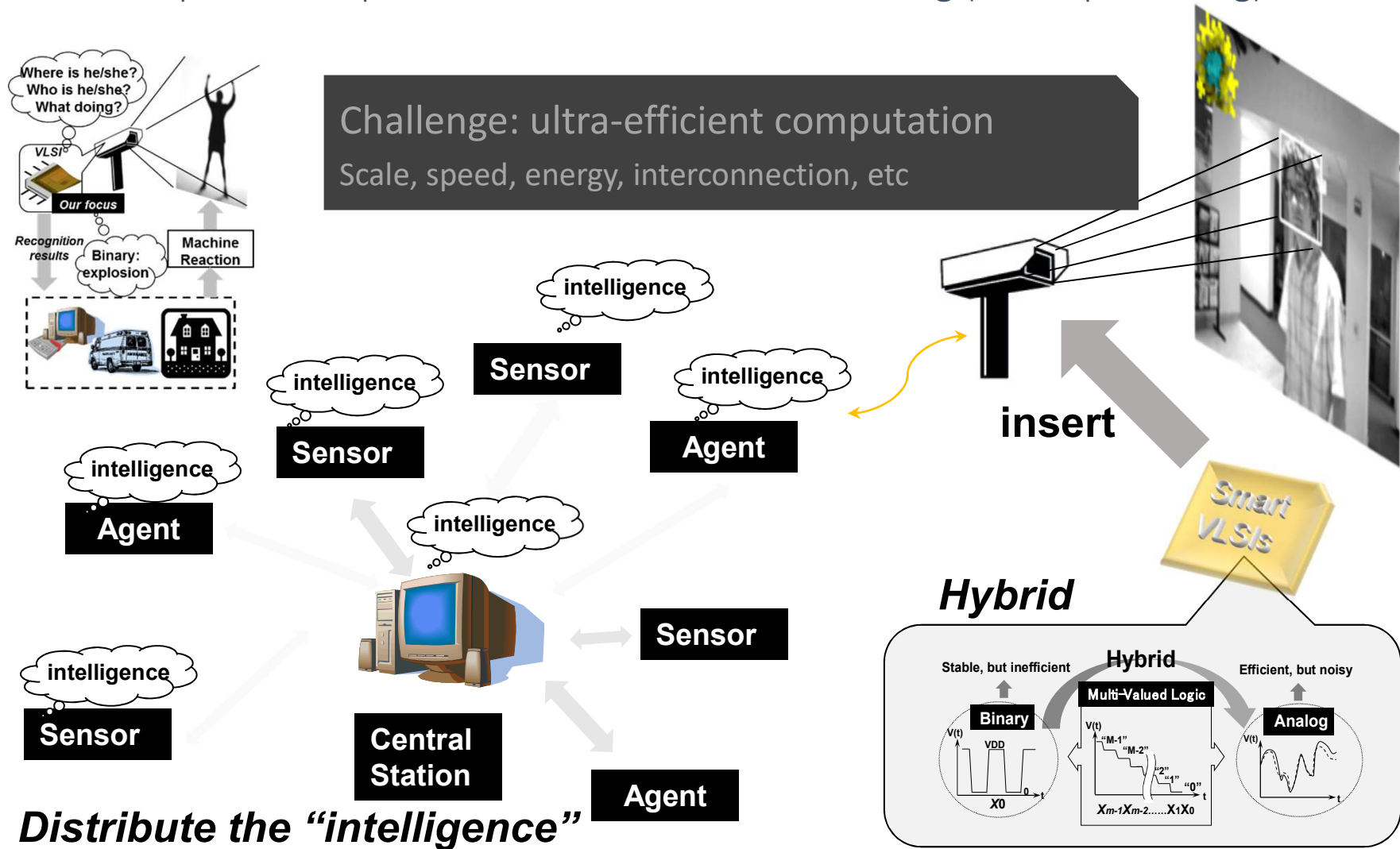
NAIST

#1

Why consider AI (VLSI) chips?

Efficient Processor in IoT

Smart chips: VLSI implementations of machine learning (on-chip learning)



How smart is our life?

- **Smart life:** Through advanced equipment, human being controls the life even the world easily. But what if the environment could respond smartly and automatically to individuals' needs and wishes? [M. Grady et al., *Science*, 2012]



Life style is changing

- Natural & Wild Life (hundreds years ago): **do everything by hands**
- Mechanical life (100 years): **do something by driving machine**
- Automatic life (50 years): **Some machines operate without driving**
- Smart life (soon?):

smart and soft agent like a bunch of stewards and servants



An example

- **Smart home**

D. Cook, *Science*, 2012

Outer of house



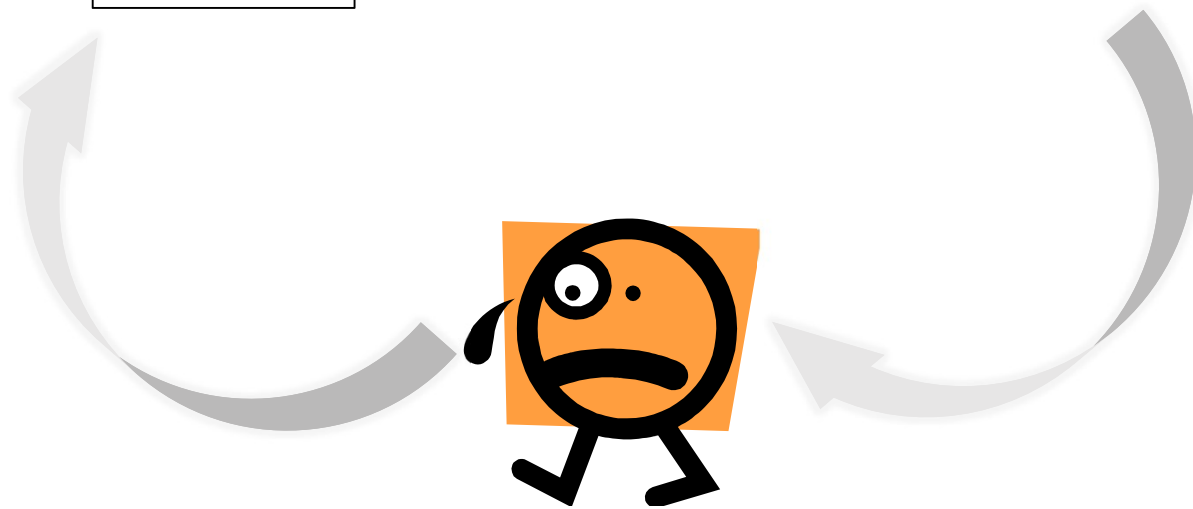
inner of house



To make environment sufficiently smart

- Key point is not automatic response, but make agents “think”.

Evidence → Decision → ~~Decision~~ → Action



Human reaction

IoT hardware on VLSI side

A large number of various VLSI devices are required

	Power	size	applications
Stationary devices	Watt	Large	Displayer, Monitor, Mechanical driver, Stationary Sensor...
Nomadic devices (Body Area Network)	Mill Watt	Small/tiny	Mobile ~, Wearable ~, Body-Embedded ~
Autonomous transducers	Micro Watt	tiny	Communication devices

Central Processing Station (computer?)

H. De Man, "Ambient Intelligence: Gigascale Dreams and Nanoscale Realities", *IEEE Int. Conf. Solid-State Circuits*, vol. 1, pp 29-35, Feb. 2005.

#2

How analog computing effects AI?

#2.1

Fully Parallel Analog VLSIs for Implementing Machine Learning

VLSI On-chip Training

- What is “on-chip training”?

$$253 \div 11 = ?$$

$$10010111 + 11011 = ?$$

Rules of solution have already been mastered



**Possible
but hard**



**Faster
Reliably**

VLSI On-chip Training

- What is “on-chip training”?



Which is caw?

Easy for human, difficult for computer.



Is it beautiful view?

No existing rules of solution for computer.





Is he a bad man?

VLSI On-chip Training

- What is “on-chip training”?

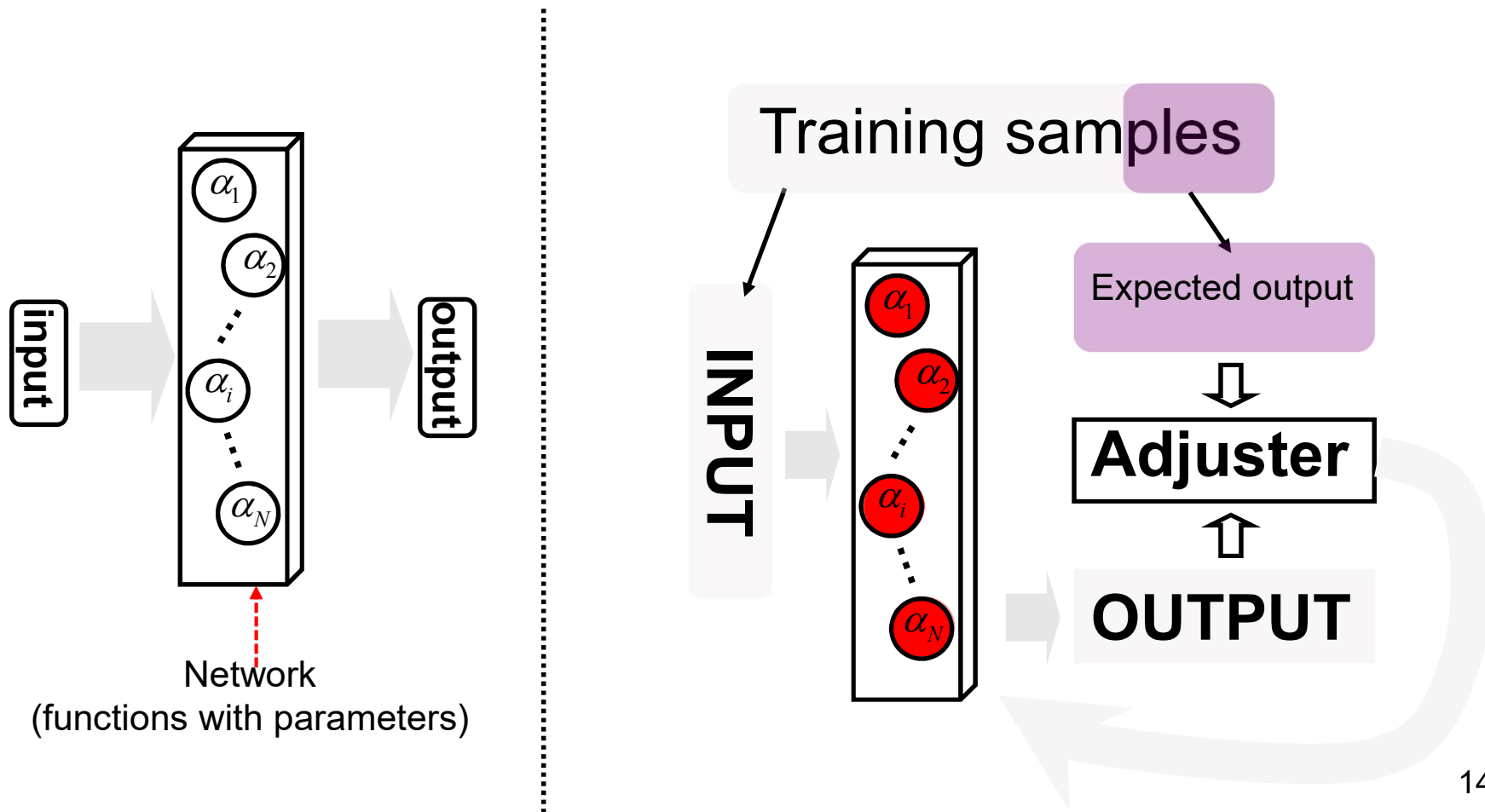


Give some learning examples, make VLSI system pursue the solving rules by itself.

	Processing elements	Element size	Energy use	Processing speed	Style of computation	Fault tolerant	learns	Intelligent, conscious
	10^{14} synapses	$10^{-6}m$	$30W$	$100Hz$	Parallel, distributed	yes	yes	usually
	10^8 transistors	$10^{-6}m$	$30W$ (CPU)	$10^9 Hz$	Serial, centralized	no	A little	Not (yet)

What is machine learning?

[Wikipedia] To learn from experience E with respect to some class of tasks T and performance measure P, if its performance at tasks in T, as measured by P, improves with experience E.



Why analog?

Fast calculation (real-time)

Smaller chip area

Fully parallel cellular architecture can be built











Non-boolean

Non-clock based

Error-tolerant

General review

- **VLSI implementation strategies**

	Hardware	Step control	Speed	Chip size	Flexibility
Fully-serial	Digital	<i>Clock-based iteration</i>			
Partially-parallel	Analog	<i>Clock-based iteration</i>			
Hyper-Parallel	Analog	<i>Non-clock Freely-feedback</i>	 		

Outline

Analog implementations of them:

- **Support Vector Machine**
- K-Quasi-Centers clustering
- On-line learning strategies
- Data domain description
- Intel Project

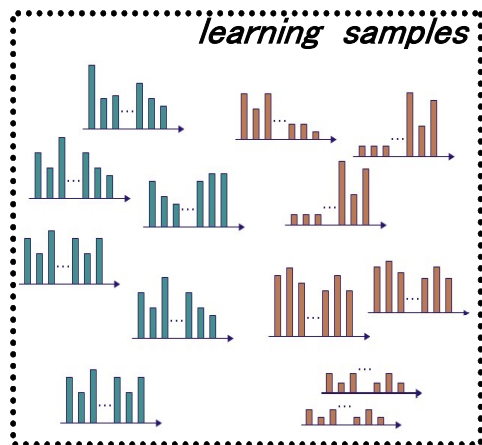
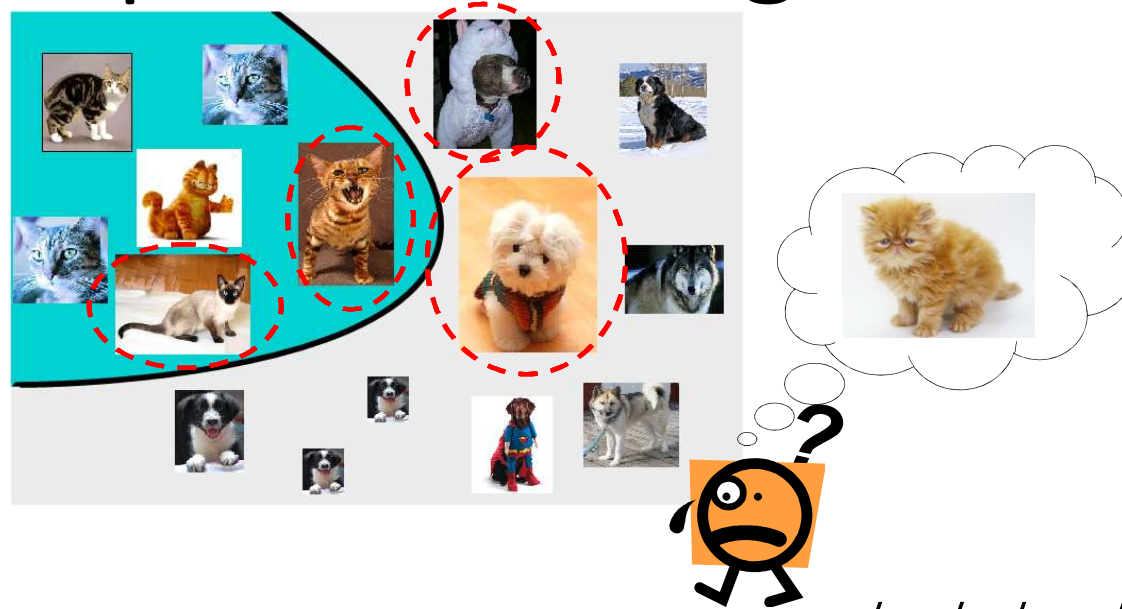
Support Vector Machine (SVM)



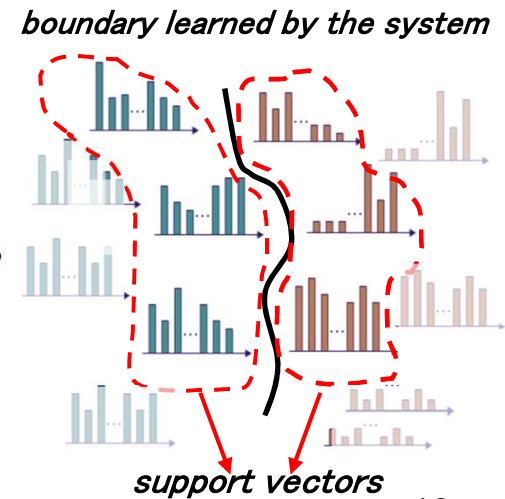
Learning samples



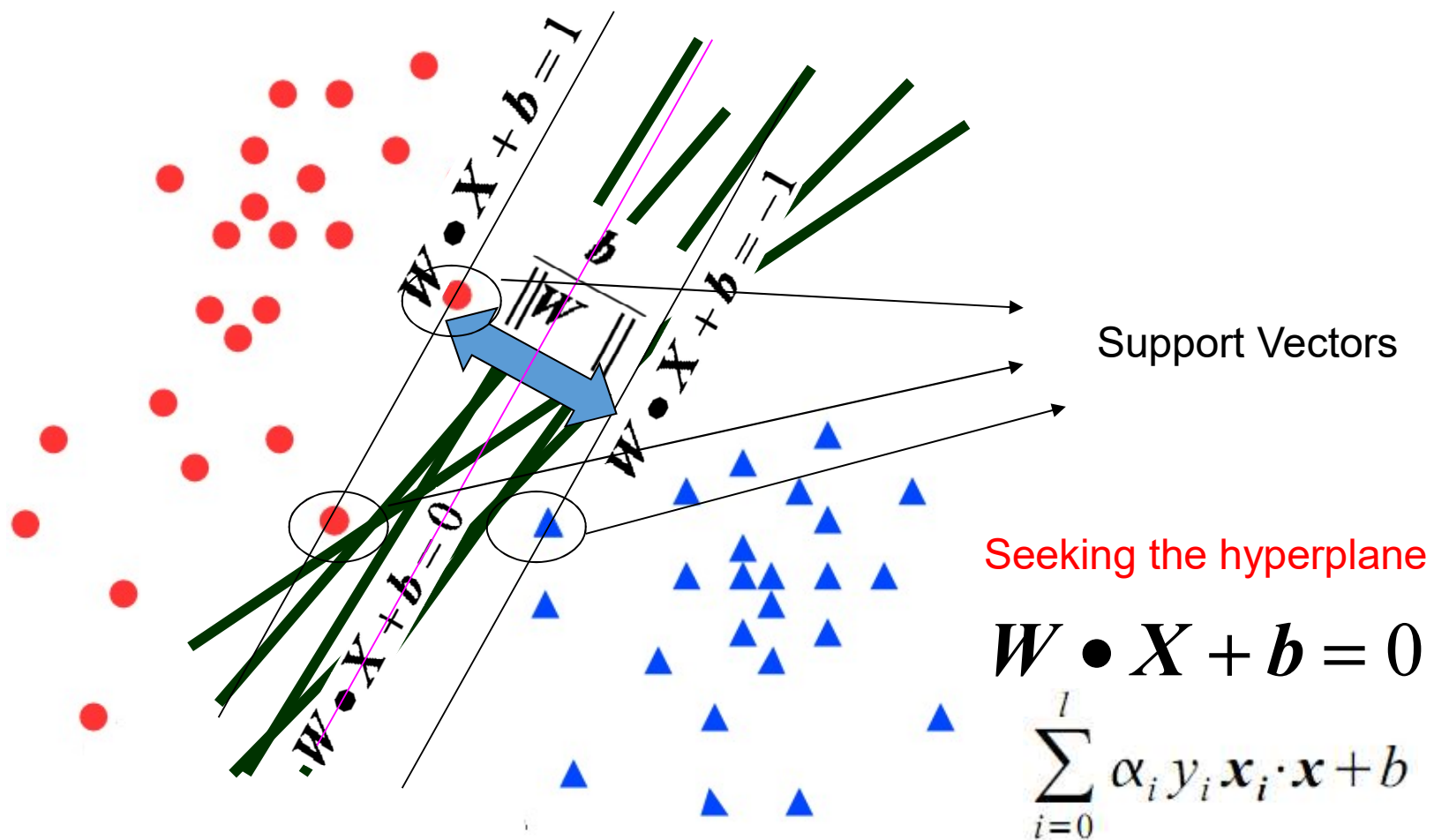
SVM for pattern recognition



SVM learning & classifying processor

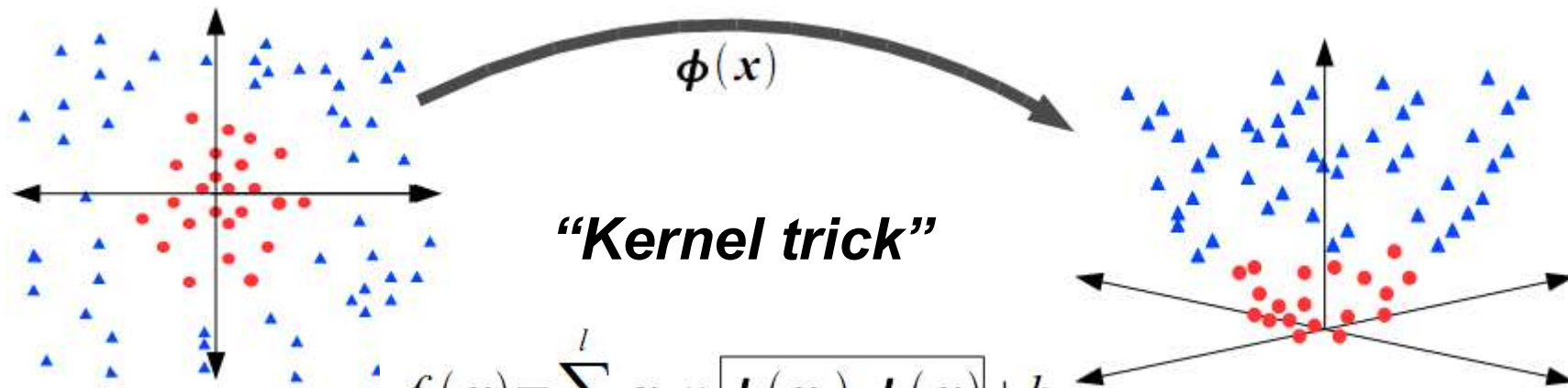


SVM for pattern recognition



SVM with “Kernel trick”

Non-linear



$$f(\mathbf{x}) = \sum_{i=1}^l \alpha_i y_i \boxed{\phi(\mathbf{x}_i) \cdot \phi(\mathbf{x})} + b$$

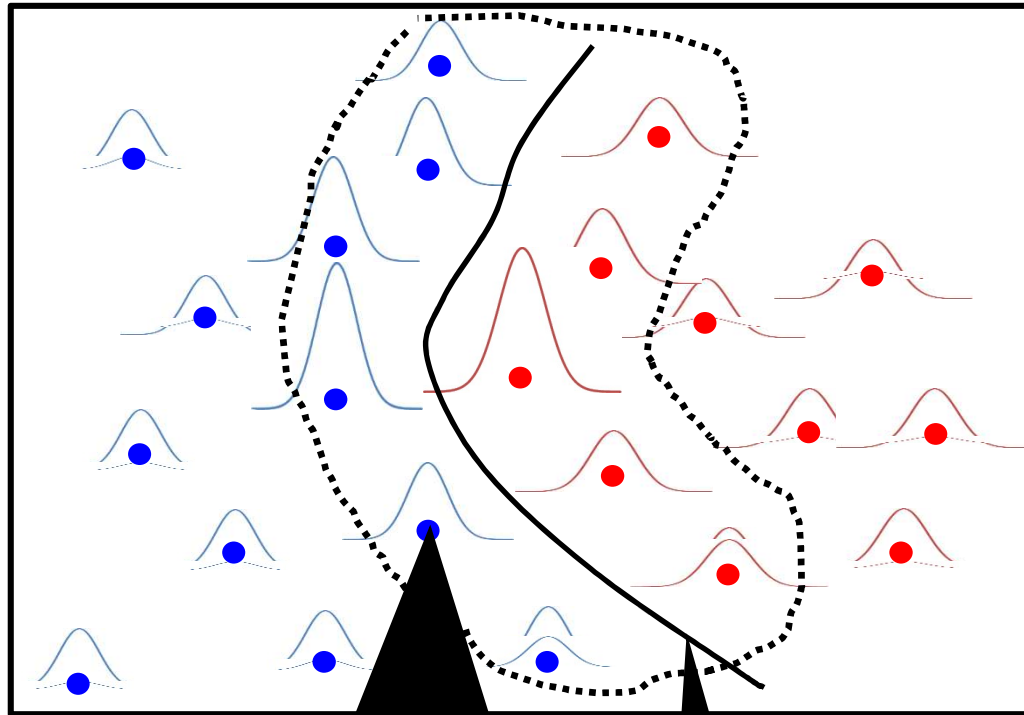
$$f(\mathbf{x}) = \sum_{i=1}^l \alpha_i y_i \boxed{K(\mathbf{x}_i, \mathbf{x})} + b$$

K = ? Linear X1-X2 ? or quadratic ?

Gaussian Kernel

$$K(\mathbf{x}_i, \mathbf{x}_j) = \exp(-\|\mathbf{x}_i - \mathbf{x}_j\|^2 / 2\sigma^2)$$

SVM learning operation

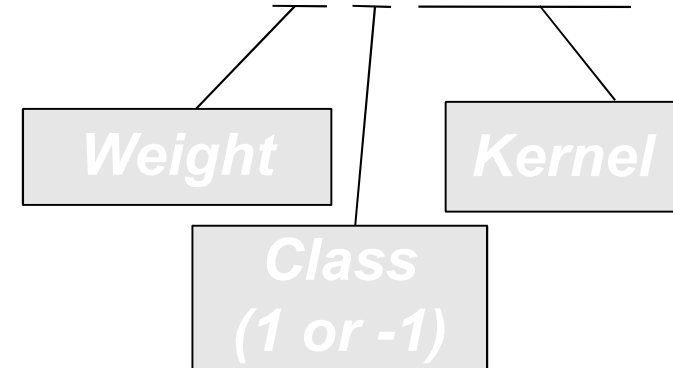


Support Vectors : x_i

**Decision Boundary
 $f(x) = 0$**

■ **Classification**

$$f(x) = \sum \alpha_i y_i e^{-|\mathbf{x}_i - \mathbf{x}|^2 / \sigma}$$

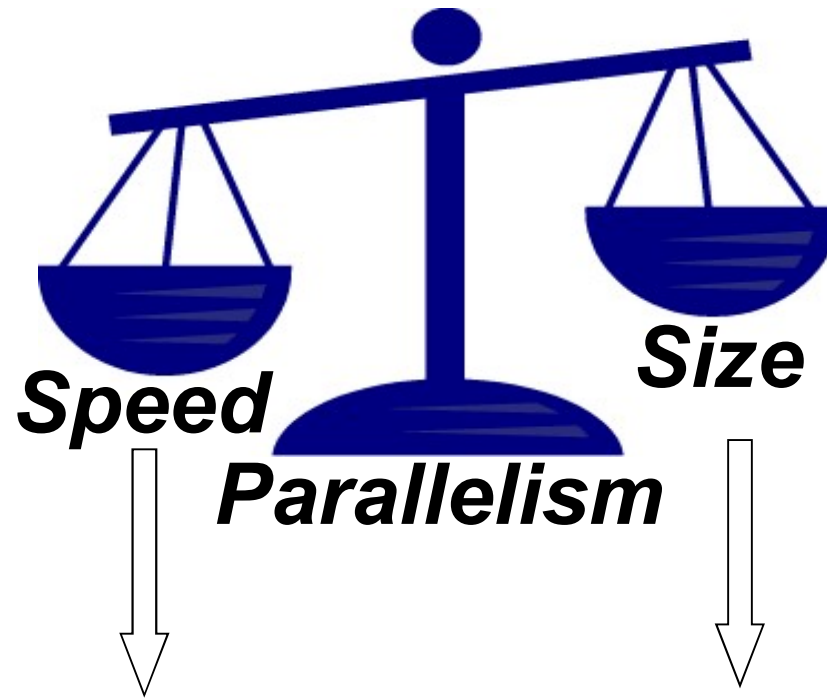


■ **Learning**

= determining weights

$$\alpha_i \leftarrow 1 - y_i \sum_{j \neq i} y_j \alpha_j e^{-|\mathbf{x}_i - \mathbf{x}_j|^2 / \sigma}$$

Analog Implementation of SVM



1. Complex computation: $A \cdot e^{-\frac{(x_{i1}-x_{j1})^2+(x_{i2}-x_{j2})^2+(x_{i3}-x_{j3})^2+(x_{i4}-x_{j4})^2+(x_{i5}-x_{j5})^2+(x_{i6}-x_{j6})^2}{\sigma}}$

→ Analog circuits to generate Gaussian function

2. Learning operation: large number of numerical iterations

→ Fully parallel architecture to avoid clock-based iterations

Analog Implementation of SVM (with Gaussian function kernel)

	Parallelism	Chip area	Learning speed	Dimensions	Chip measurement
S.-Y. Peng et al. (2008)	<i>Fully parallel</i>	$\propto N^2$	<i>One clock</i>	2	<i>N.A</i>
K. Kang et al. (2010)	<i>Row-parallel</i>	$\propto N$	$\propto N \times i$	2	<i>Available</i>
Target of this work	<i>Fully Parallel</i>	$\propto N$	<i>One clock</i>	64	<i>Available</i>

N: number of learning samples

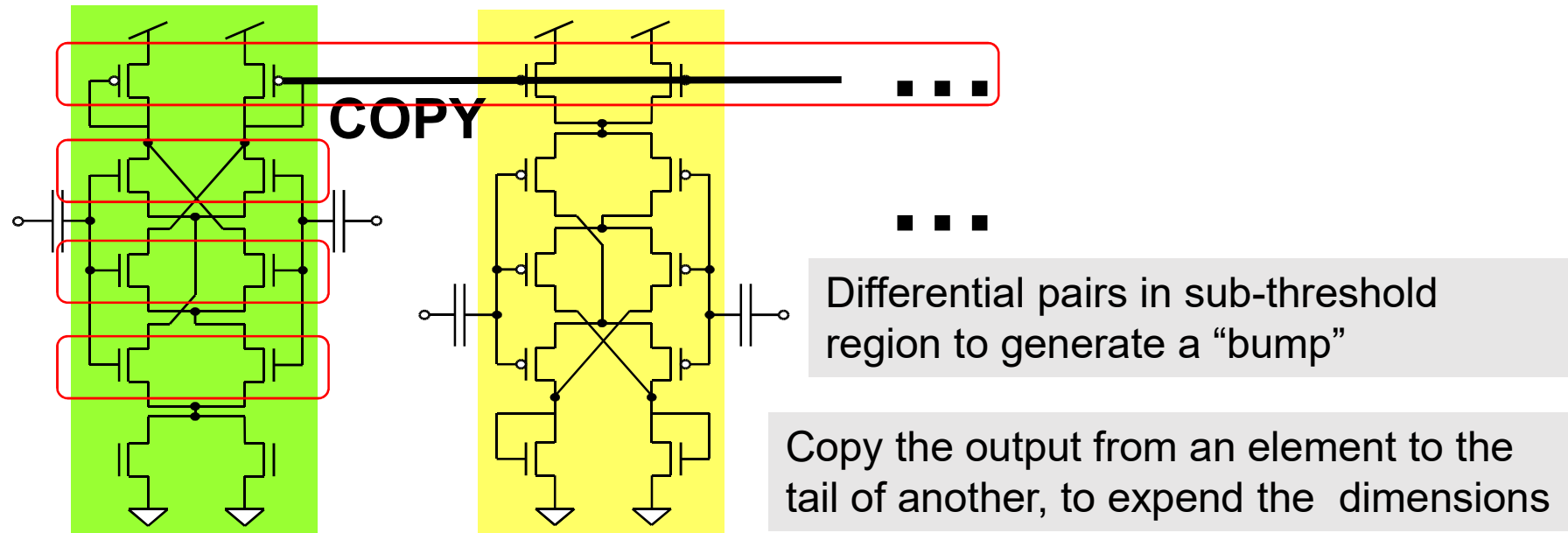
i: number of numerical iterations

[1] S.-Y. Peng, B. A. Minch, and P. E. Hasler: *Proc. Int. Symp. Circuits Syst.*, 2008, pp. 860 - 863.

[2] K. Kang and T. Shibata: *IEEE Trans. Circuits Syst.*, Vol. 57, no. 7, pp. 1513 – 1524 (2010).

Gaussian-generation circuit

Traditional Gaussian-generation circuit: Bump circuit *



$$\begin{array}{ccc}
 e^{-(x_{i1} - x_{j1})^2} & \times & e^{-(x_{i2} - x_{j2})^2} \times \dots \\
 \text{Error by mismatch} & & \text{Error by mismatch} \\
 5\% & & 5\% \longrightarrow \mathbf{2270\%!} \\
 & & \mathbf{(64D)}
 \end{array}$$

*K. Kang and T. Shibata: *IEEE Trans. Circuits Syst.*, Vol. 57, no. 7, pp. 1513 – 1524 (2010).²⁵

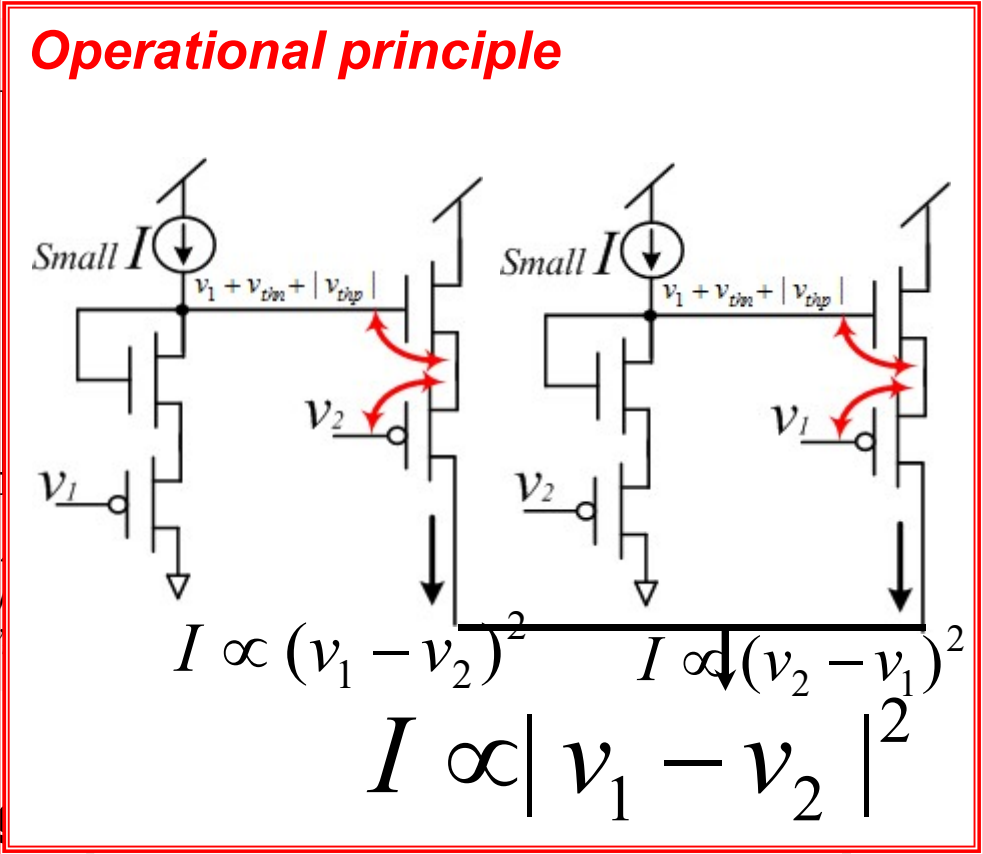
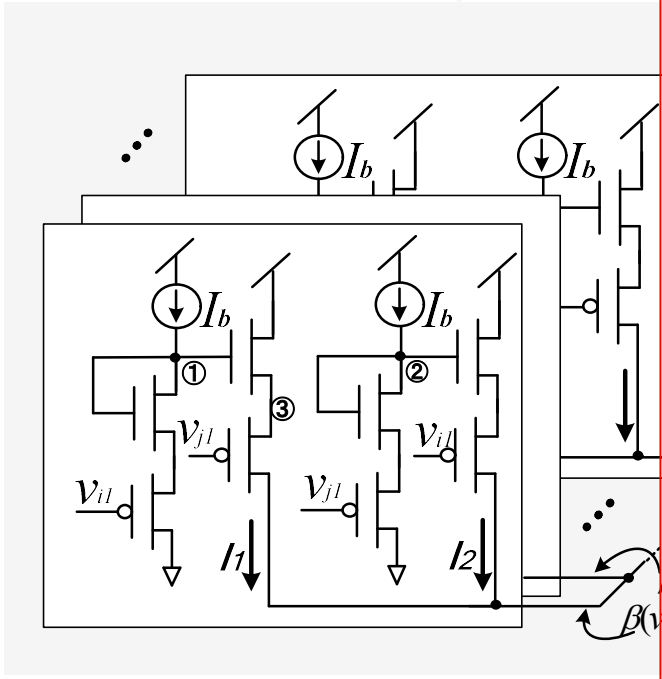
Gaussian-generation circuit

Our Proposed Gaussian-generation circuit

$$\frac{(v_{i1} - v_{j1})^2 + (v_{i2} - v_{j2})^2 + (v_{i3} - v_{j3})^2 + \dots + (v_{i64} - v_{j64})^2}{\sigma}$$

$I_c \cdot e$

σ

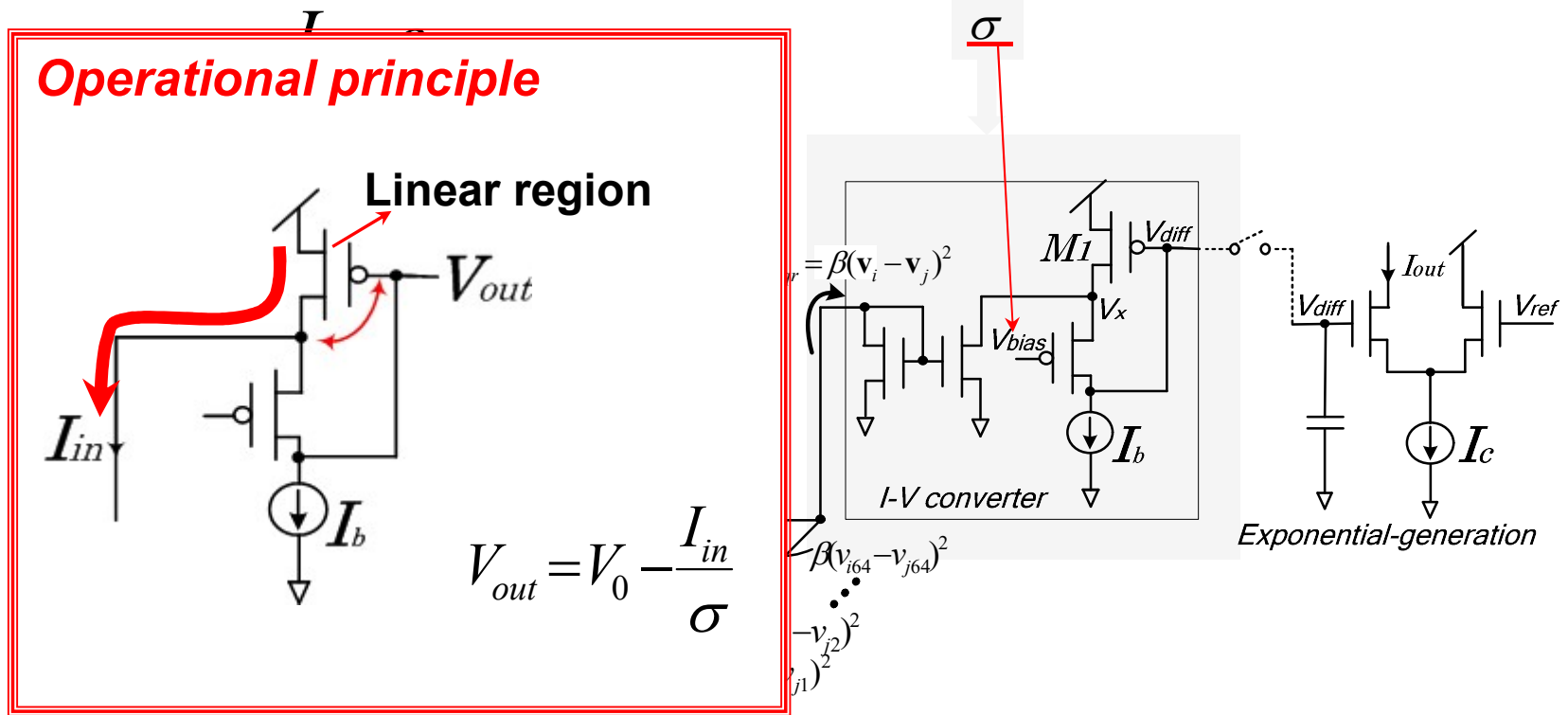


Euclidean **Lar**

Gaussian-generation circuit

Our Proposed Gaussian-generation circuit

$$\frac{(v_{i1} - v_{j1})^2 + (v_{i2} - v_{j2})^2 + (v_{i3} - v_{j3})^2 + \dots + (v_{i64} - v_{j64})^2}{\sigma}$$



Euclidean *Large*

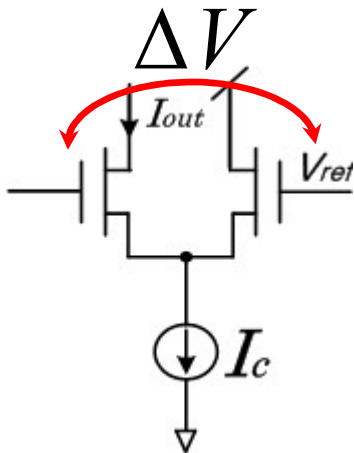
Exp. *Small*

Gaussian-generation circuit

Our Proposed Gaussian-generation circuit

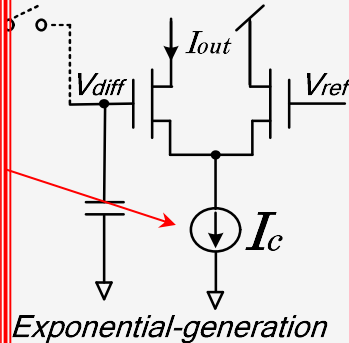
$$I_c \cdot e^{\frac{(v_{i1}-v_{j1})^2 + (v_{i2}-v_{j2})^2 + (v_{i3}-v_{j3})^2 + \dots + (v_{i64}-v_{j64})^2}{\sigma}}$$

Operational principle



$$I_{out} \approx \frac{I_c}{2} \cdot e^{\frac{q}{kT} \Delta V}$$

Unbalance of differential pair



Exponential-generation

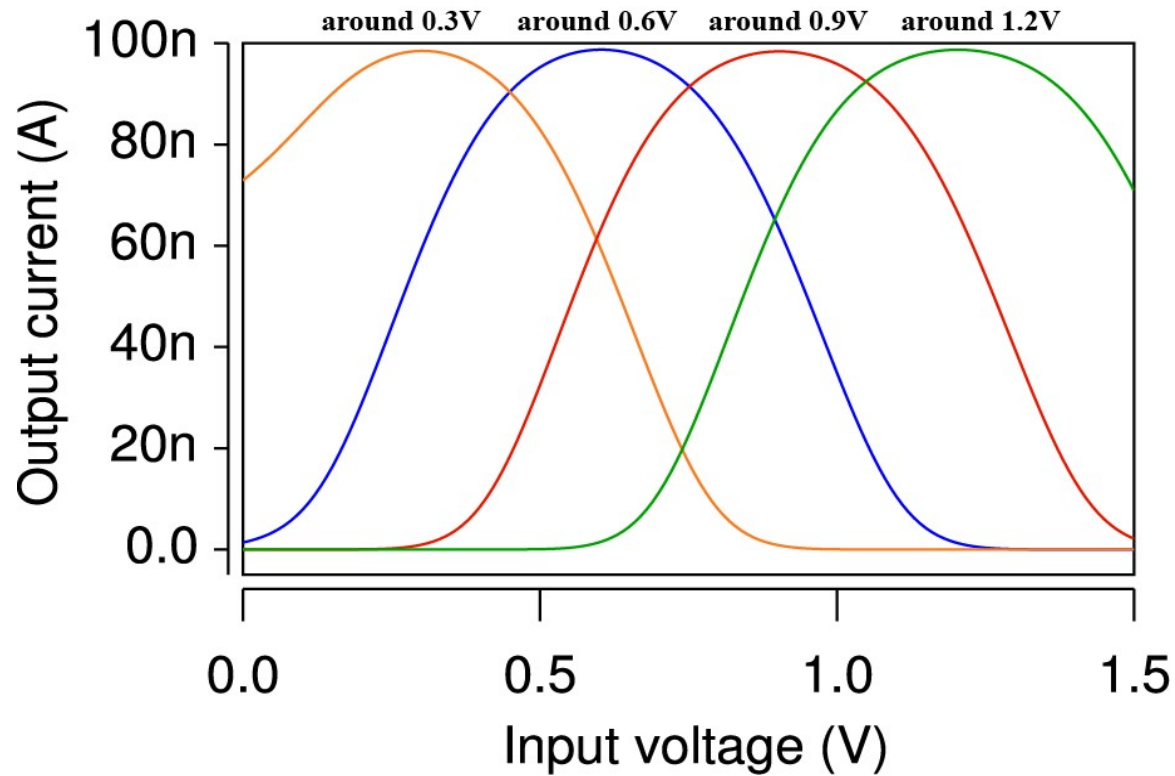
s to self-tune I_c

Euclidean Large Exp. Small

Gaussian-generation circuit

Performance of Our Proposed Gaussian-generation circuit

Center value of Gaussian function feature can be dynamically programmed



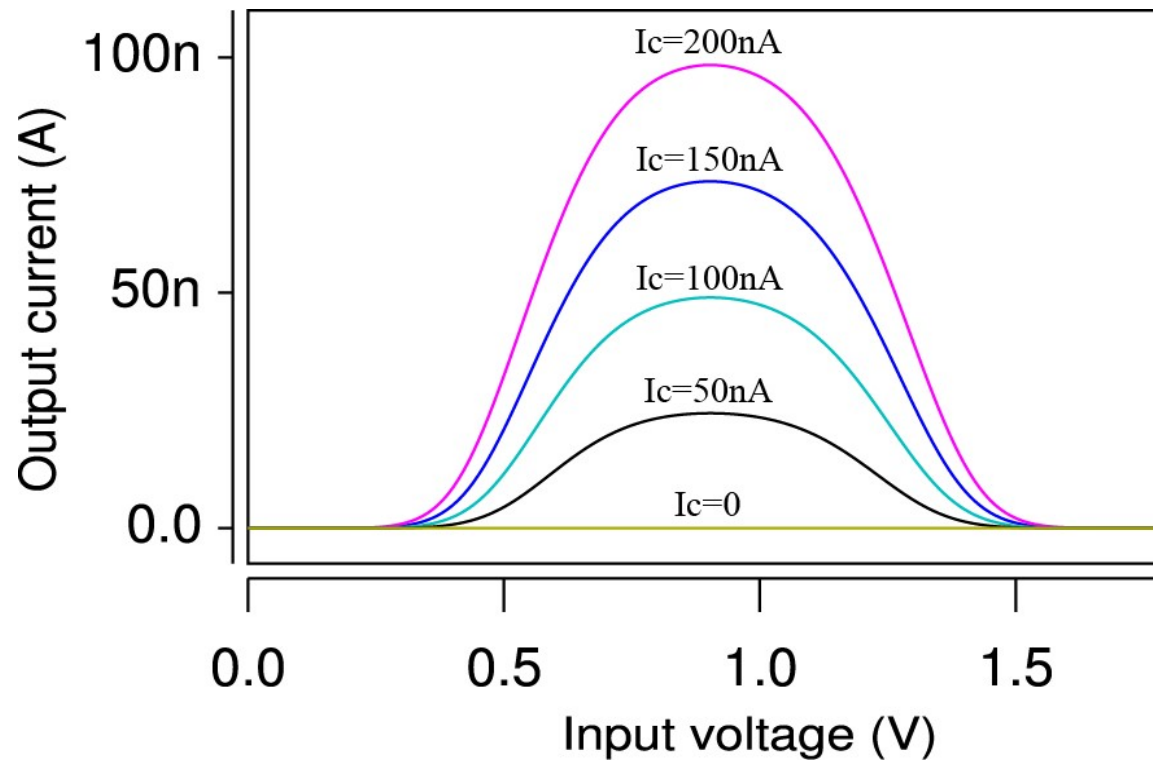
Simulation

$$I_c \cdot e^{-\frac{(v_{i1}-v_{j1})^2+(v_{i2}-v_{j2})^2+(v_{i3}-v_{j3})^2+\dots+(v_{i64}-v_{j64})^2}{\sigma}}$$

Gaussian-generation circuit

Performance of Our Proposed Gaussian-generation circuit

Peak-height of Gaussian function feature can be dynamically programmed



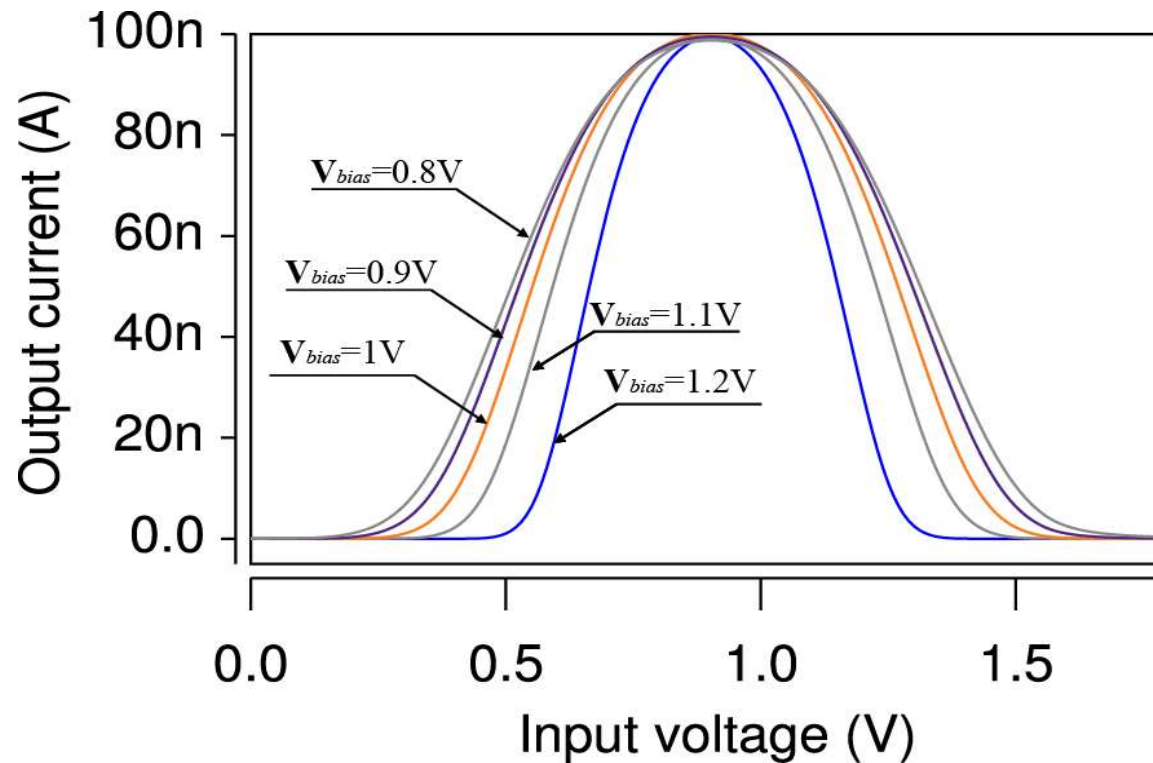
Simulation

$$I_c \cdot e^{-\frac{(v_{i1}-v_{j1})^2+(v_{i2}-v_{j2})^2+(v_{i3}-v_{j3})^2+\dots+(v_{i64}-v_{j64})^2}{\sigma}}$$

Gaussian-generation circuit

Performance of Our Proposed Gaussian-generation circuit

Width of Gaussian function feature can be dynamically programmed



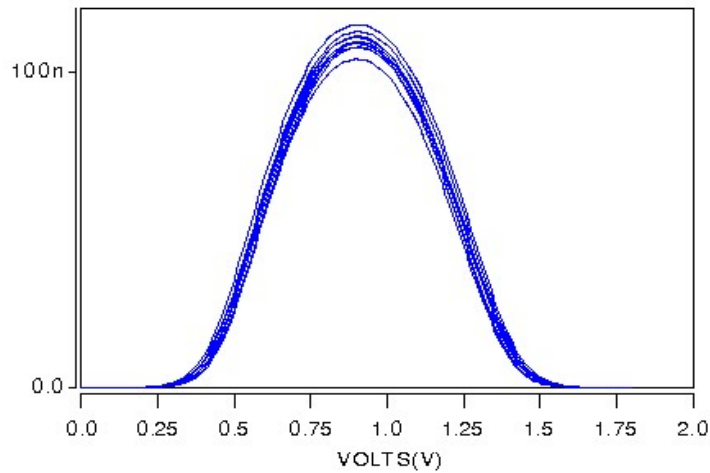
Simulation

$$I_c \cdot e^{-\frac{(v_{i1}-v_{j1})^2+(v_{i2}-v_{j2})^2+(v_{i3}-v_{j3})^2+\dots+(v_{i64}-v_{j64})^2}{\sigma}}$$

Gaussian-generation circuit

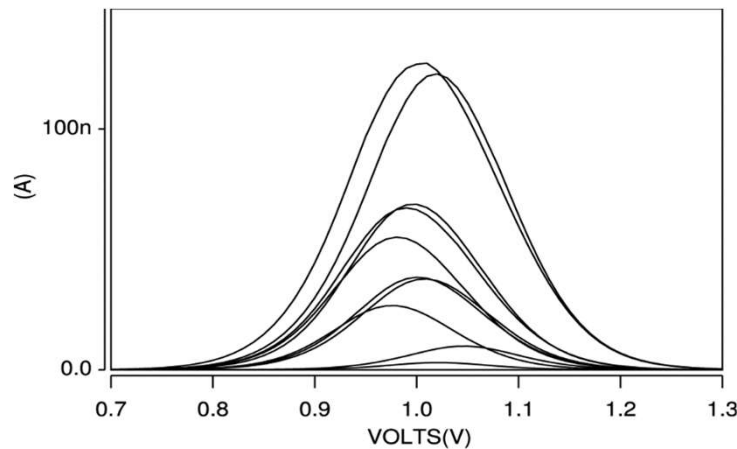
Performance of Our Proposed Gaussian-generation circuit

Reliability of proposed Gaussian generation circuit:



Monte Carlo Simulation

Reliability of traditional Gaussian generation circuit:

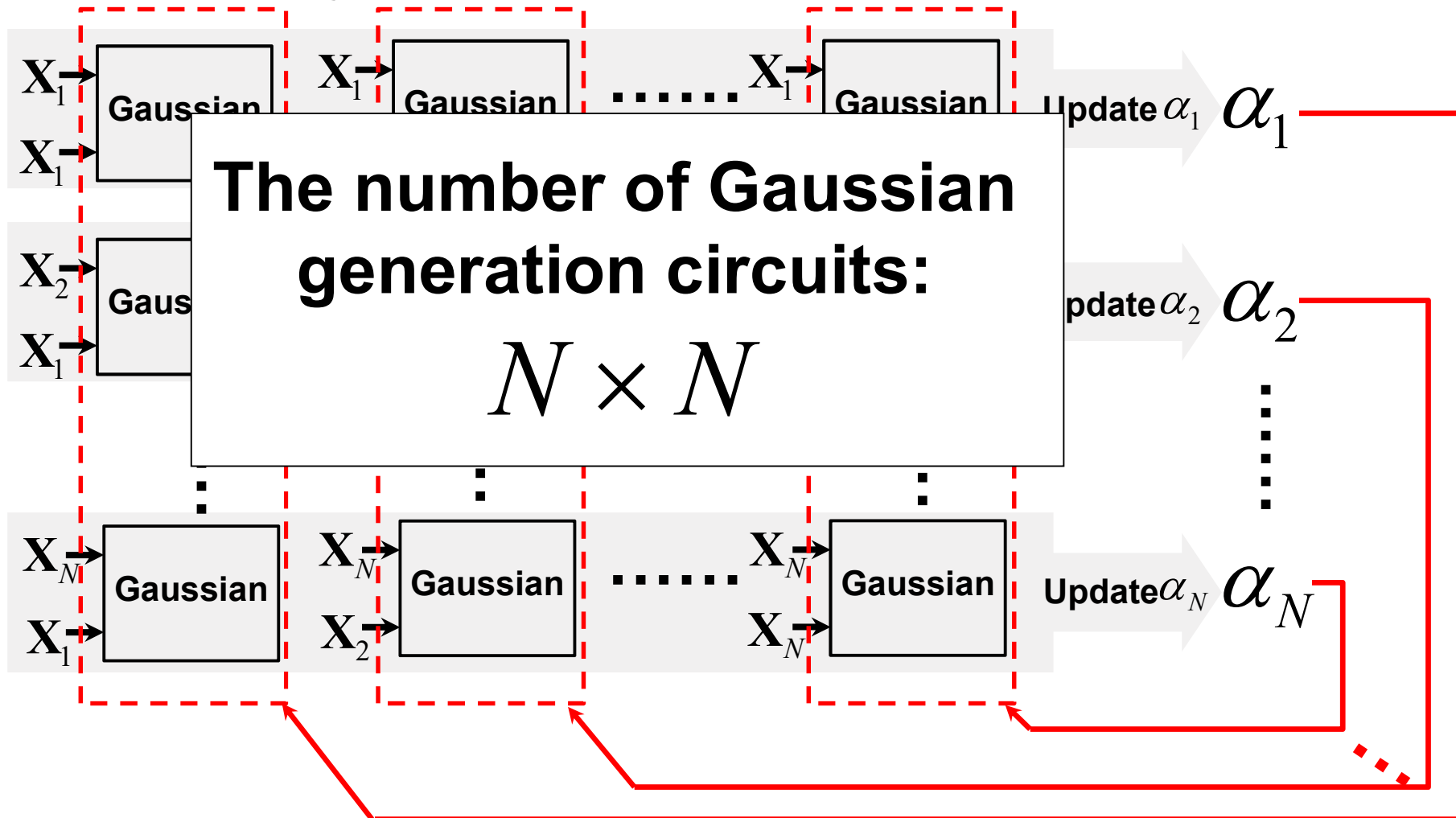


5% variation on Vth

Monte Carlo Simulation

Fully parallel architecture for SVM

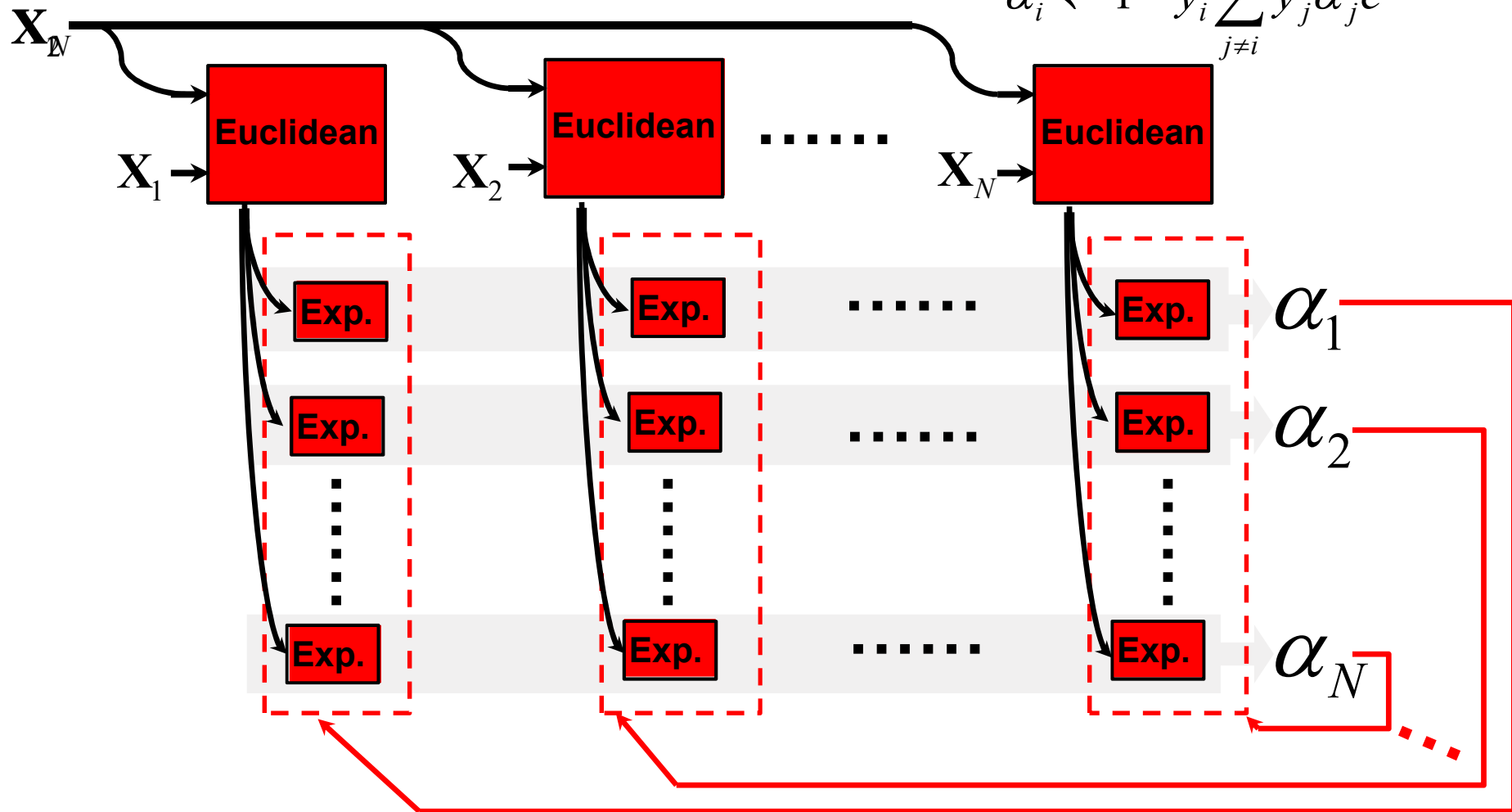
Traditional Fully parallel architecture for SVM



Fully parallel architecture for SVM

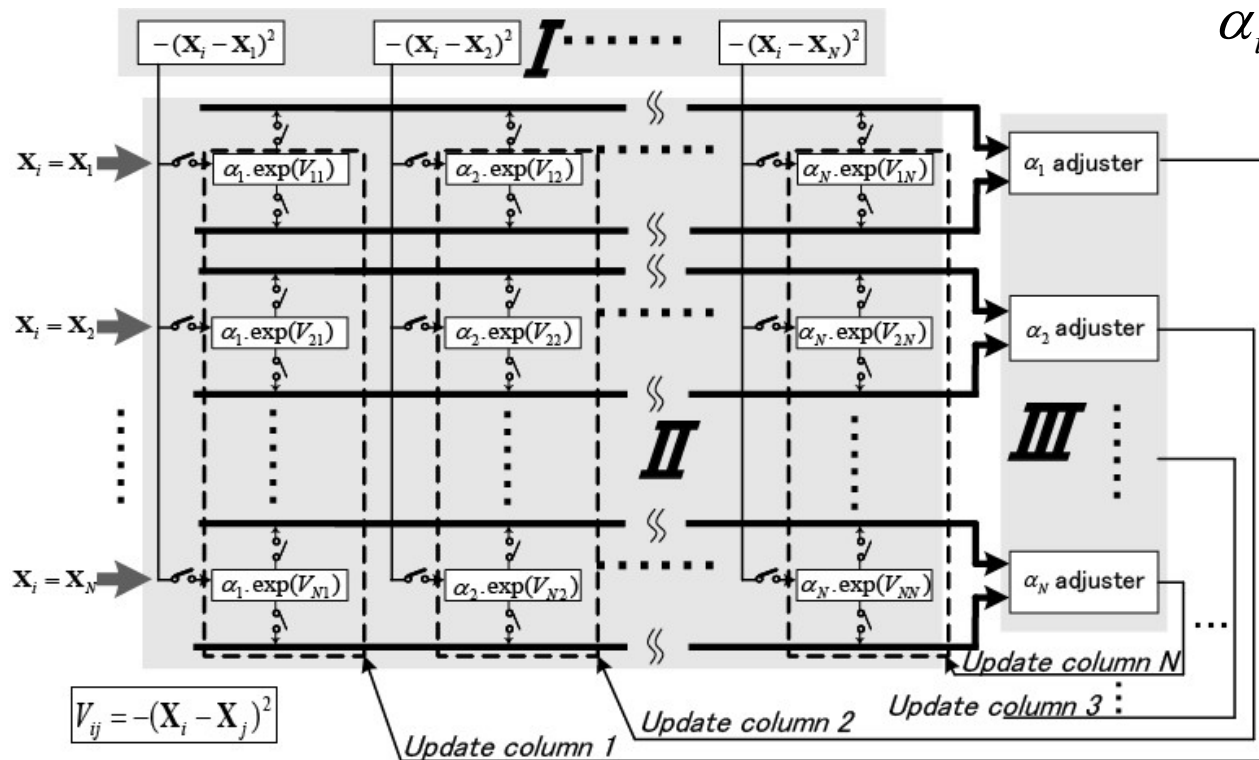
Proposed fully parallel learning architecture for SVM

$$\alpha_i \leftarrow 1 - y_i \sum_{j \neq i} y_j \alpha_j e^{-|\mathbf{x}_i - \mathbf{x}_j|^2 / \sigma}$$



Fully parallel architecture for SVM

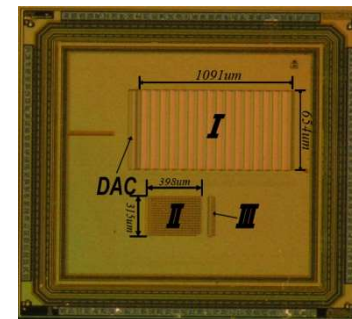
Organization of SVM processor



$$\alpha_i \leftarrow 1 - y_i \sum_{j \neq i} y_j \alpha_j e^{-|X_i - X_j|^2 / \sigma}$$

Non-iterative based
Freely analog feedback

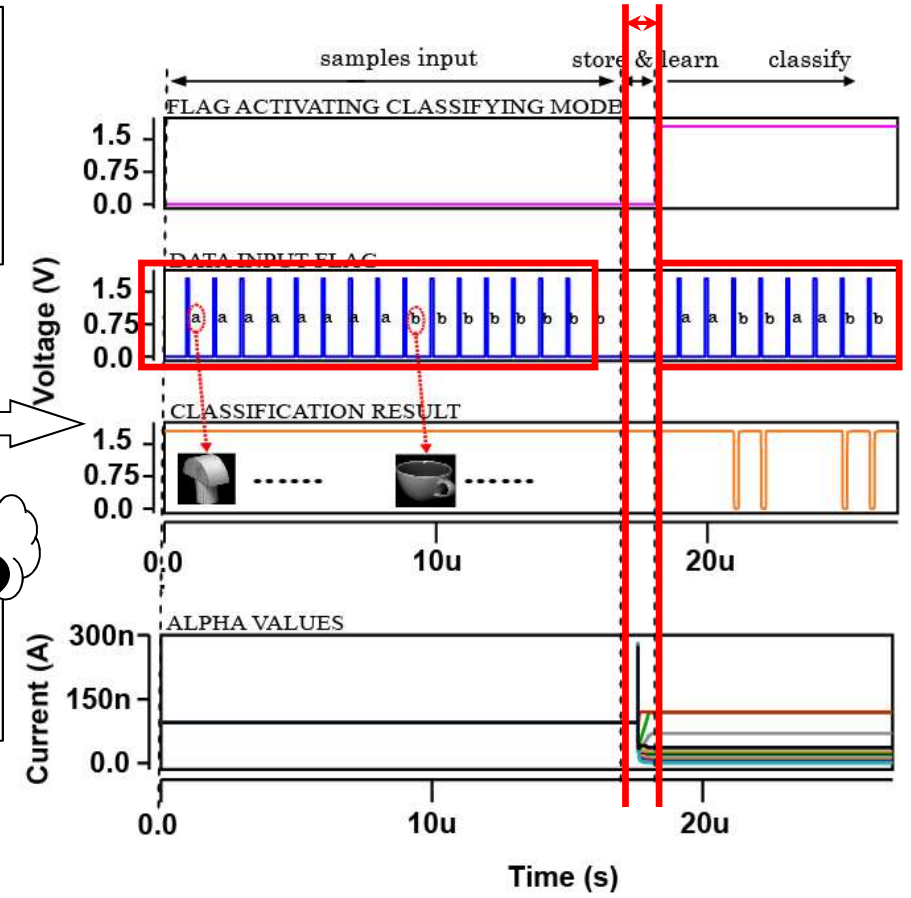
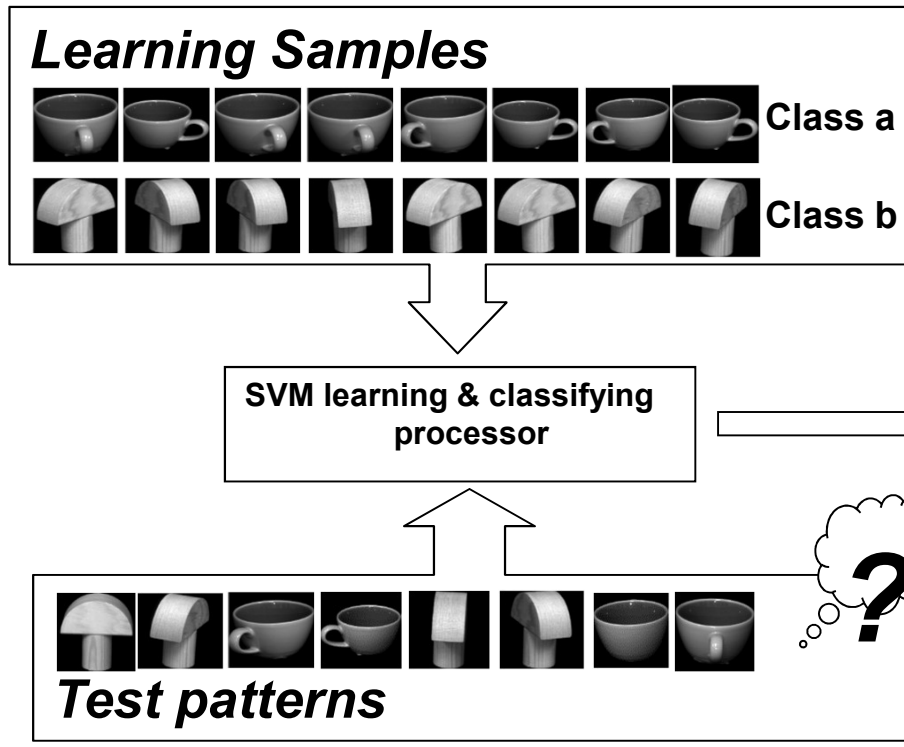
- ✓ Fast learning and self-converging
- ✓ Compact chip-area



Verification of SVM processor

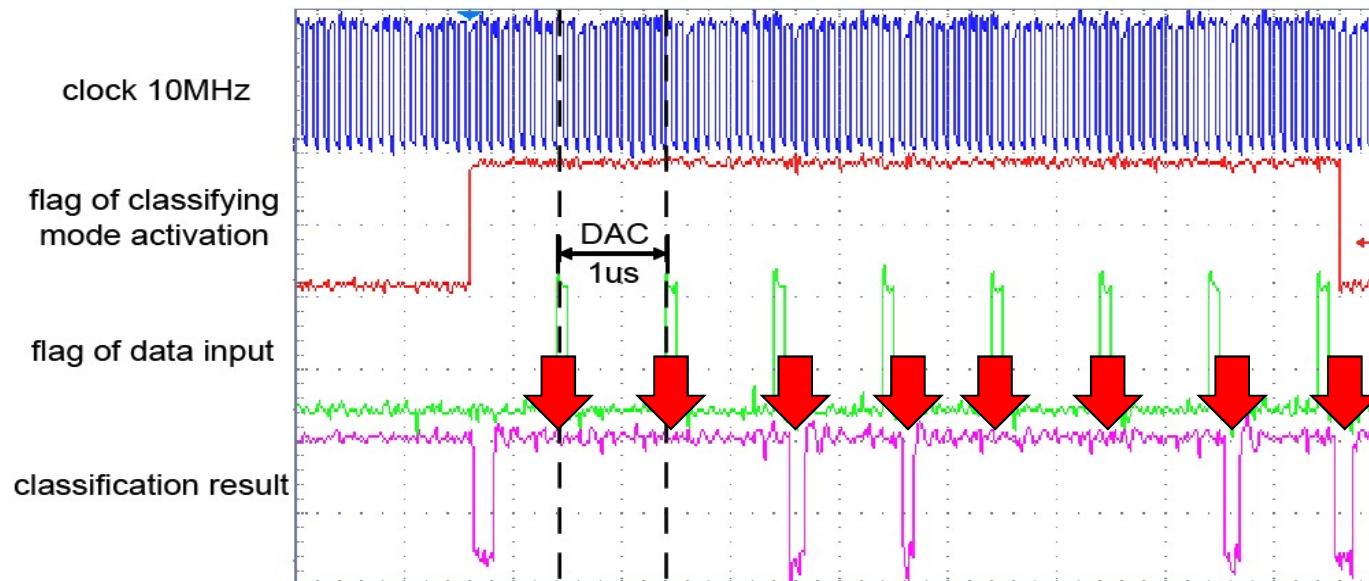
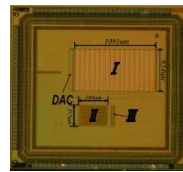
~~Learning setup~~ DAC session

Simulation



Verification of SVM processor

Chip measurement



Performance of SVM Processor

Comparisons

	[1] ISCAS ²⁰⁰⁸	[2] TCAS ²⁰¹⁰	This work
Technology	Simulation	0.18 μ m CMOS	0.18 μ m CMOS
Operation	Learning/Classifying	Learning/Classifying	Learning/Classifying
Learning parallelism	Fully parallel	Row parallel	Fully parallel
Kernel function	Gaussian	Gaussian	Gaussian
No. of kernels	$4 \times 4 + 4$	12	18.8*
Input vector	Analog voltage	Digital (8 bits)	Digital (8 bits)
Number of samples	4	12	16
Number of dimensions	2	2	1 ~ 64
Learning time (ns)	N/A	$12 \times l \times 60^\ddagger$	100
Classifying speed (vectors/s)	N/A	8.7×10^5	10^6

*The number of kernels is evaluated from the viewpoint of chip area.

\ddagger l is the number of iterations for convergence.

[1] S.-Y. Peng, B. A. Minch, and P. E. Hasler: *Proc. Int. Symp. Circuits Syst.*, 2008, pp. 860 - 863.

[2] K. Kang and T. Shibata: *IEEE Trans. Circuits Syst.*, Vol. 57, no. 7, pp. 1513 – 1524 (2010).

Support Vector Machine

Summary

Proposed architecture can be actually applied in SVM, with improved performances

R. Zhang and T. Shibata, SSDM, 2011.

R. Zhang and T. Shibata, JJAP, 2012.

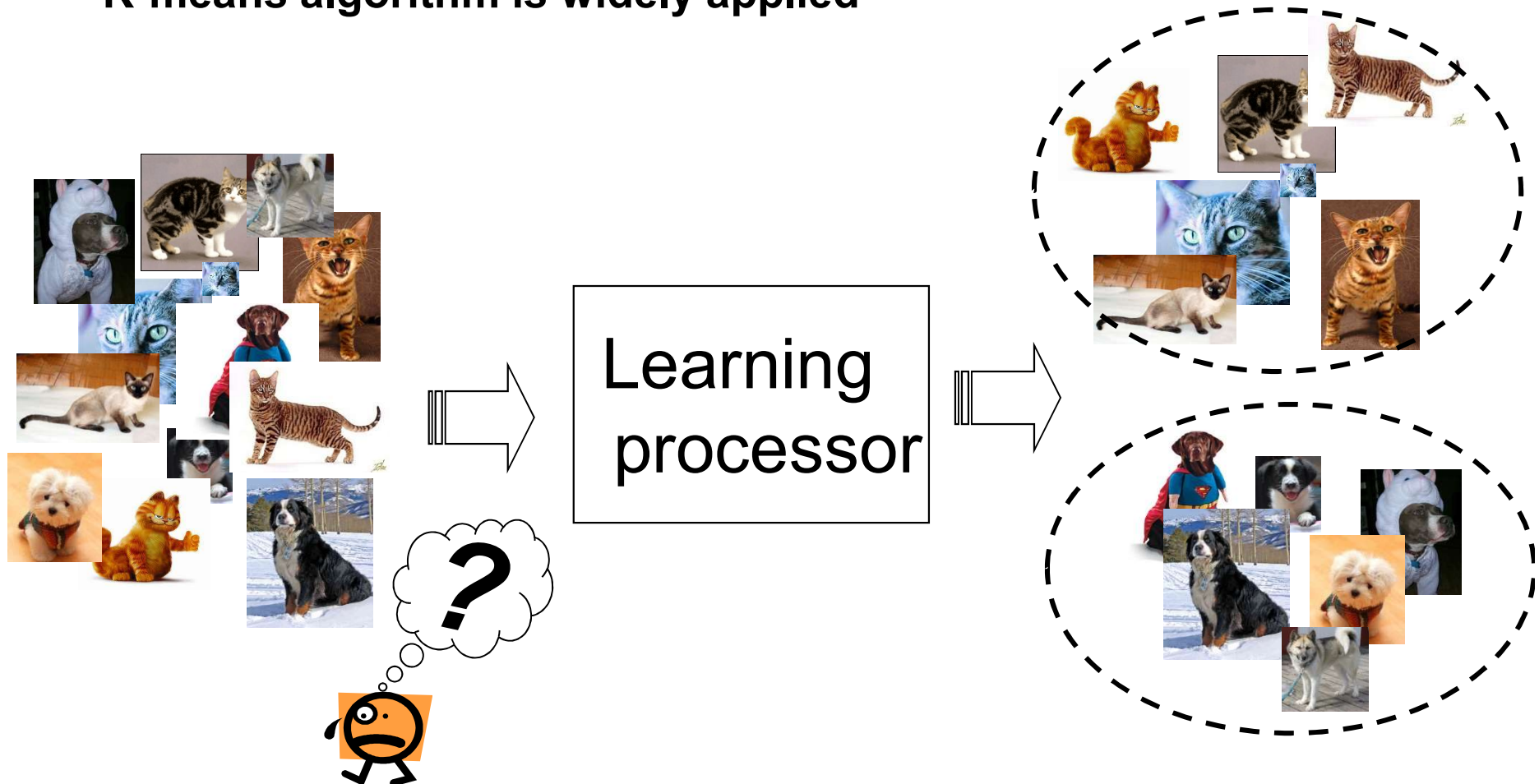
Outline

Analog implementations of them:

- Support Vector Machine
- **K-Quasi-Centers clustering**
- On-line learning strategies
- Data domain description
- Intel Project

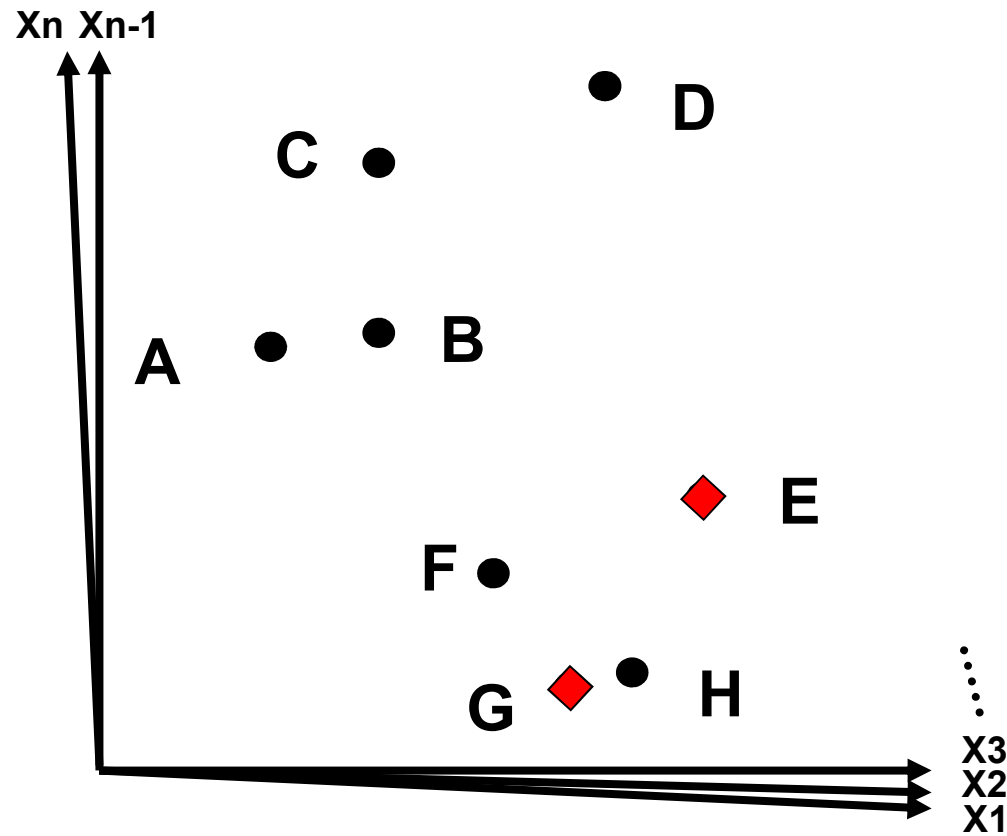
Pattern clustering

- **Patterns are clustered into categories according to the similarity**
- **K-means algorithm is widely applied**



Pattern clustering

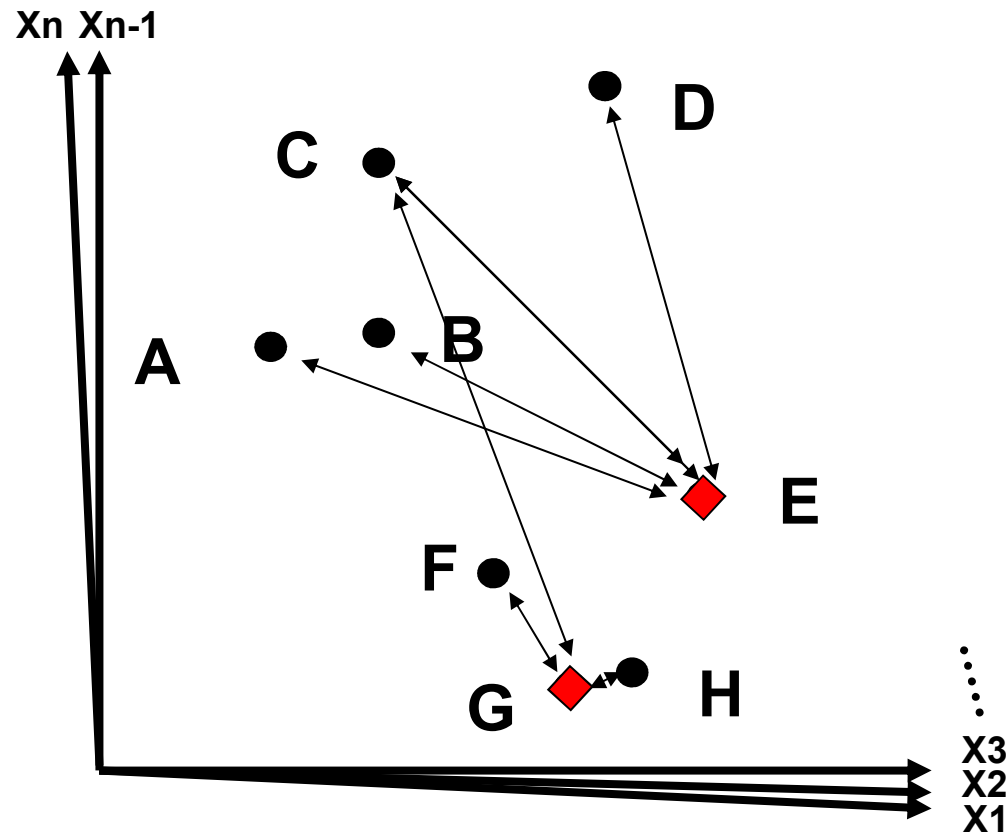
➤ Original K-means



(1) Select an initial cluster center

Pattern clustering

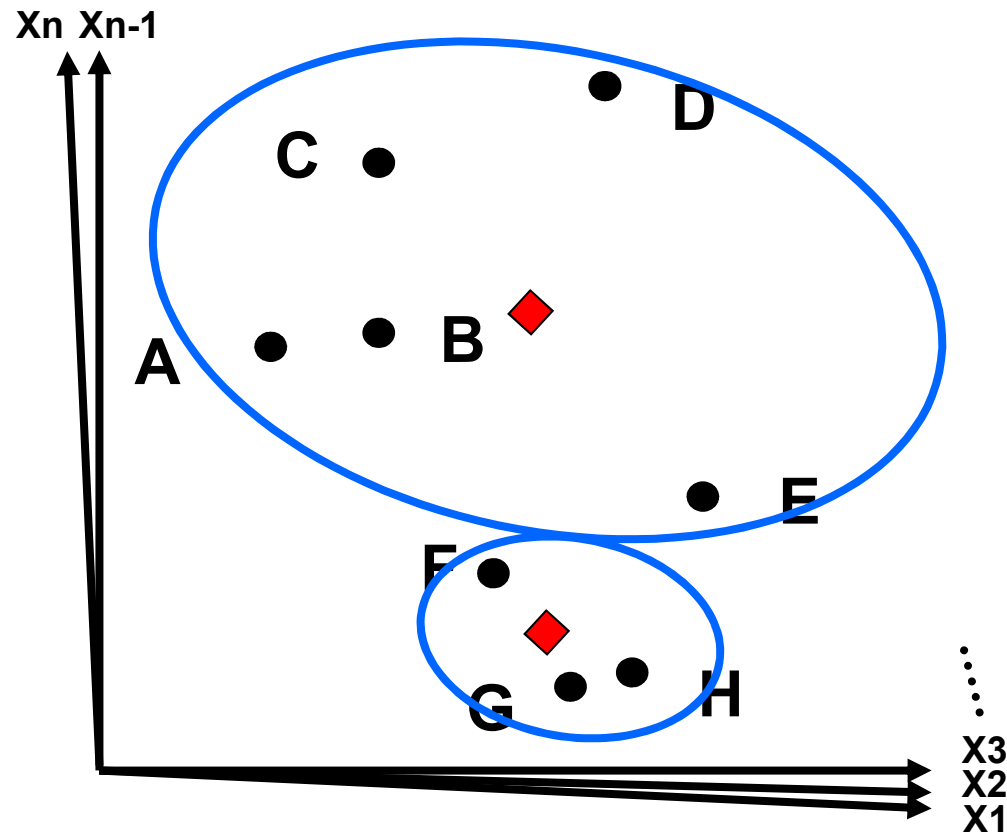
➤ Original K-means



(2) Compute the distance from the cluster center

Pattern clustering

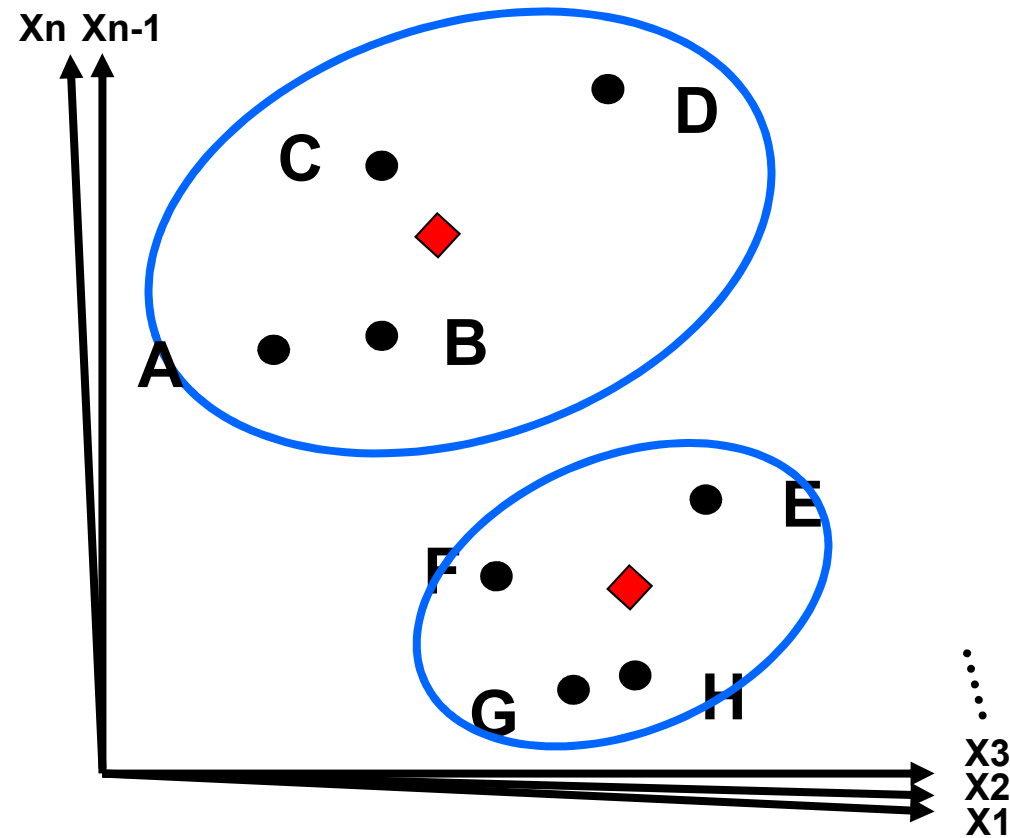
➤ Original K-means



(3) Form cluster and update cluster center as centroid of patterns

Pattern clustering

➤ Original K-means



(4) Repeat the step (2) and step(3) Until the stop condition is satisfied.

Pattern clustering

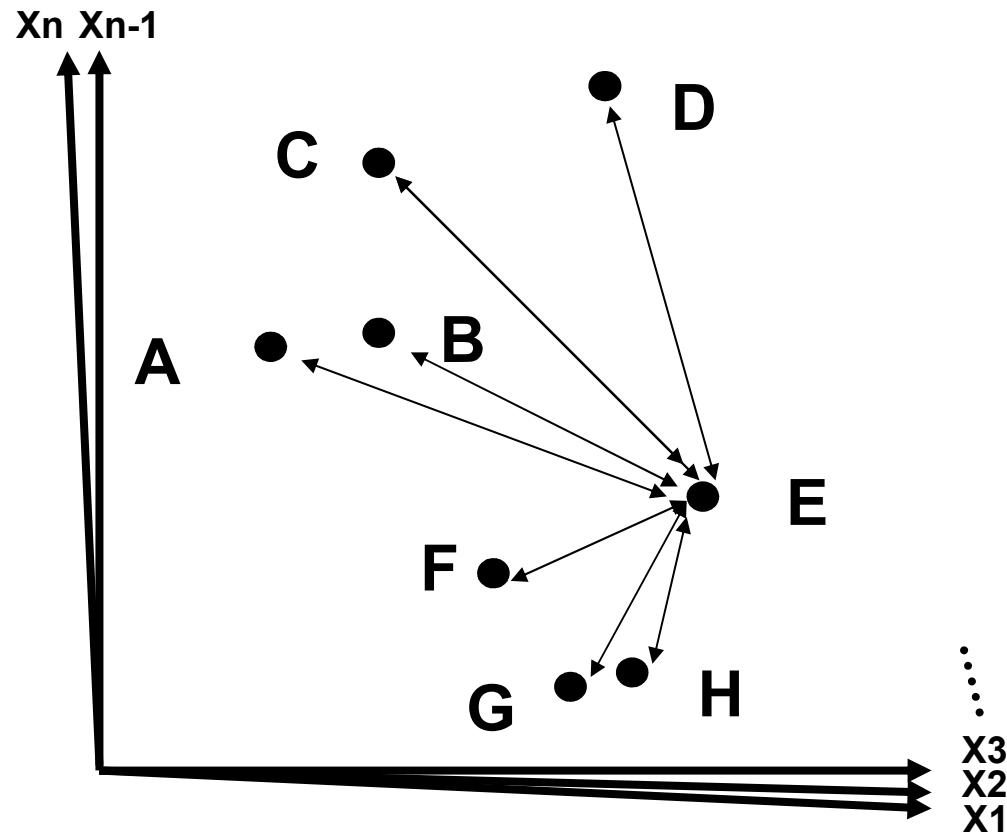
- **Original K-means**

Plenty of calculations among **vectors,
hardly implemented in parallel.**

**K-Quasi-Centers (KQC) is proposed as the
parallel-architecture-friendly version of K-means.**

K-Quasi-Centers clustering

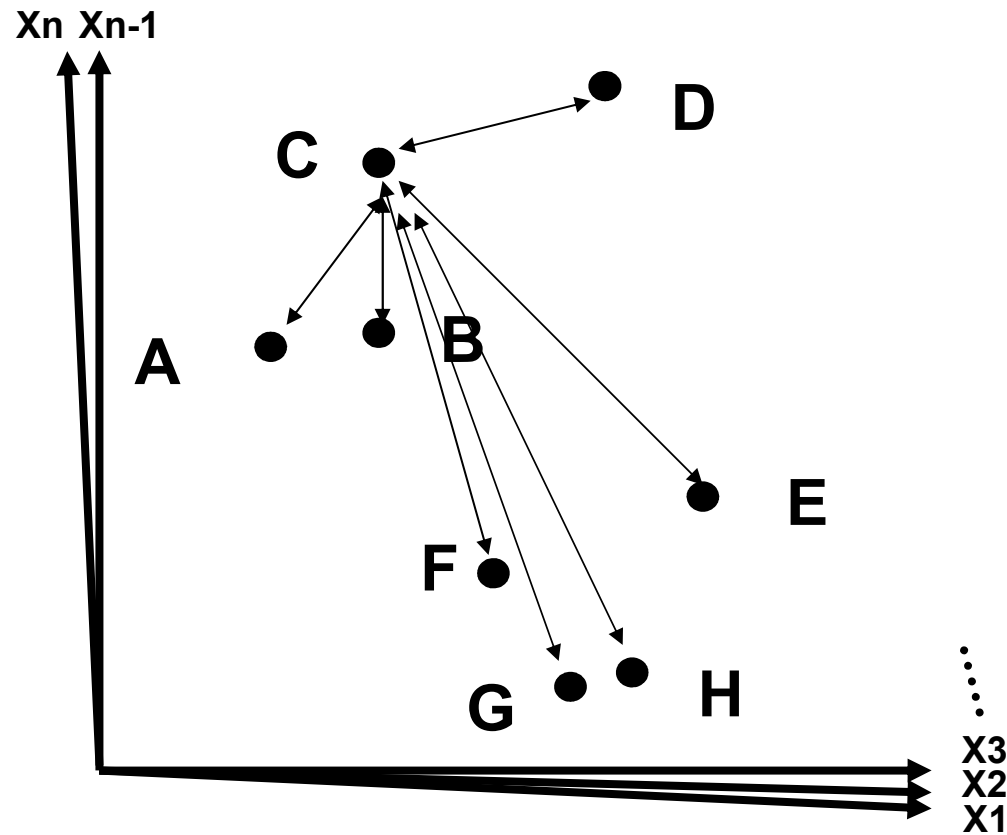
➤ Our basic idea



(1) Compute all the Euclidean distances and store them

K-Quasi-Centers clustering

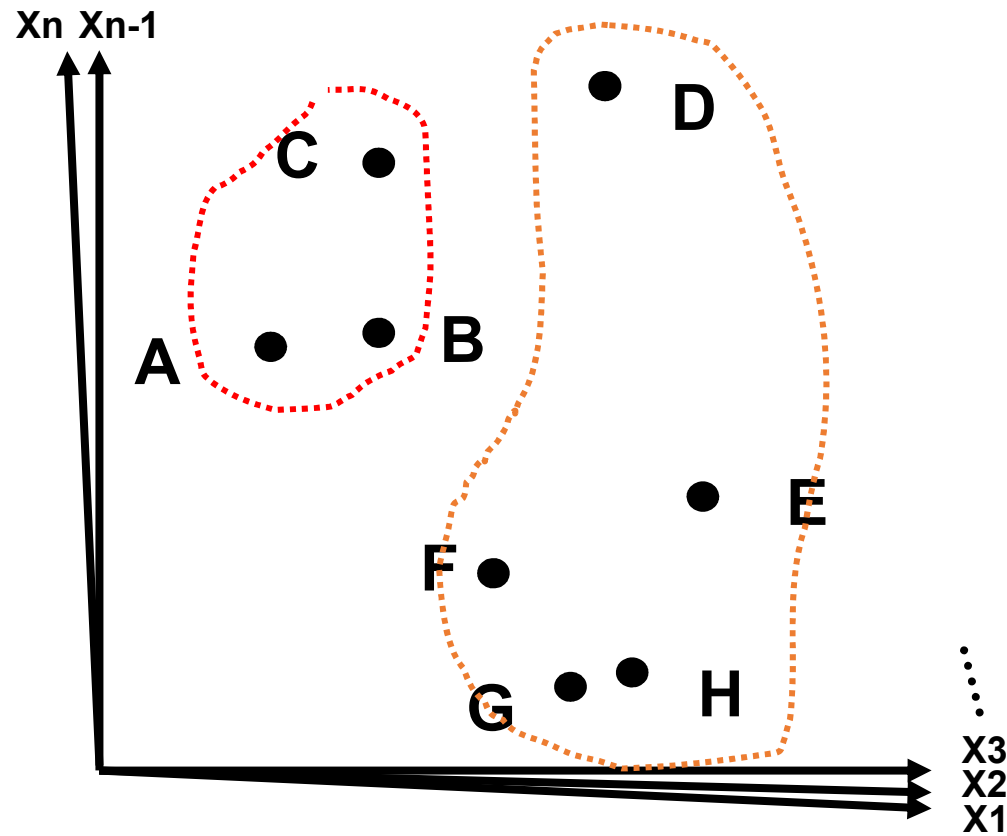
➤ Our basic idea



(1) Compute all the Euclidean distances and store them

K-Quasi-Centers clustering

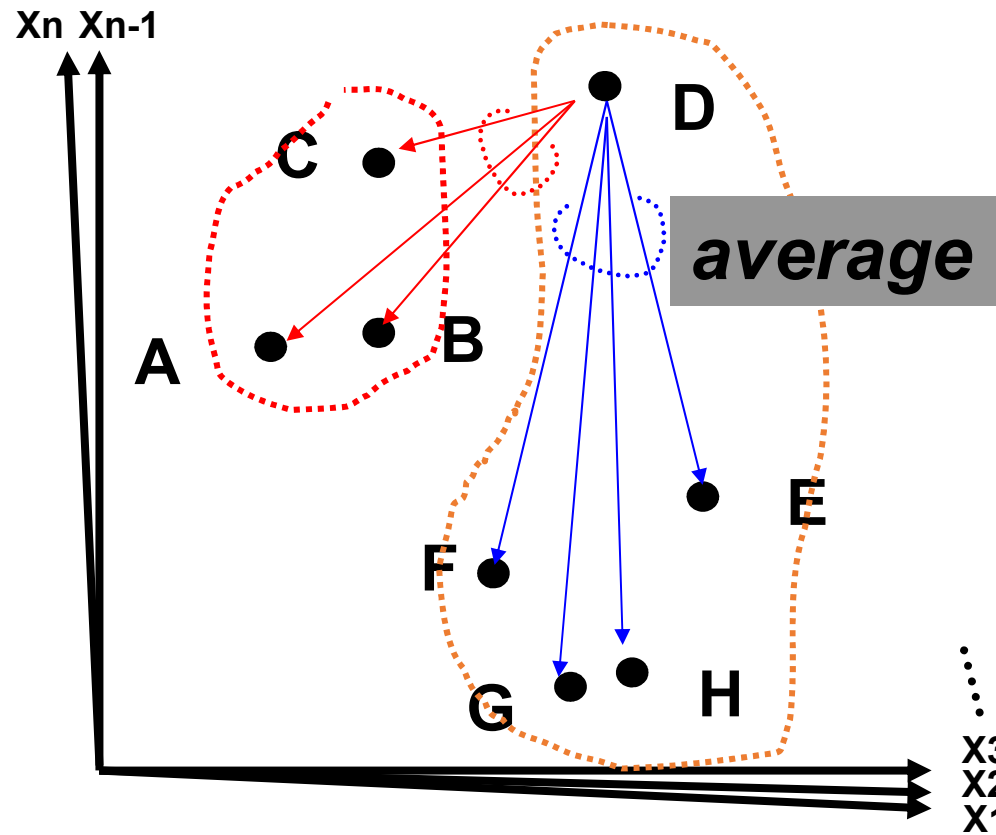
➤ Our basic idea



(2) Initialize the clustering randomly

K-Quasi-Centers clustering

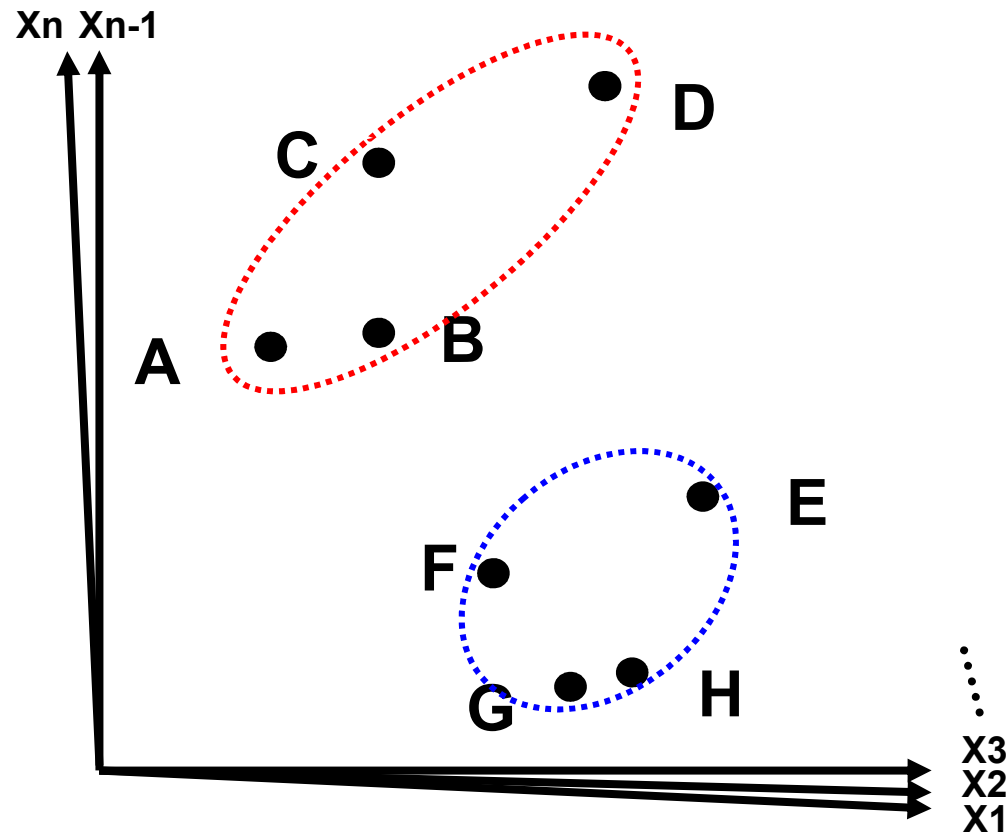
➤ Our basic idea



(3) Updating the clustering form by **scalar** calculation

K-Quasi-Centers clustering

➤ Our basic idea



(4) Repeating till converge

K-Quasi-Centers clustering

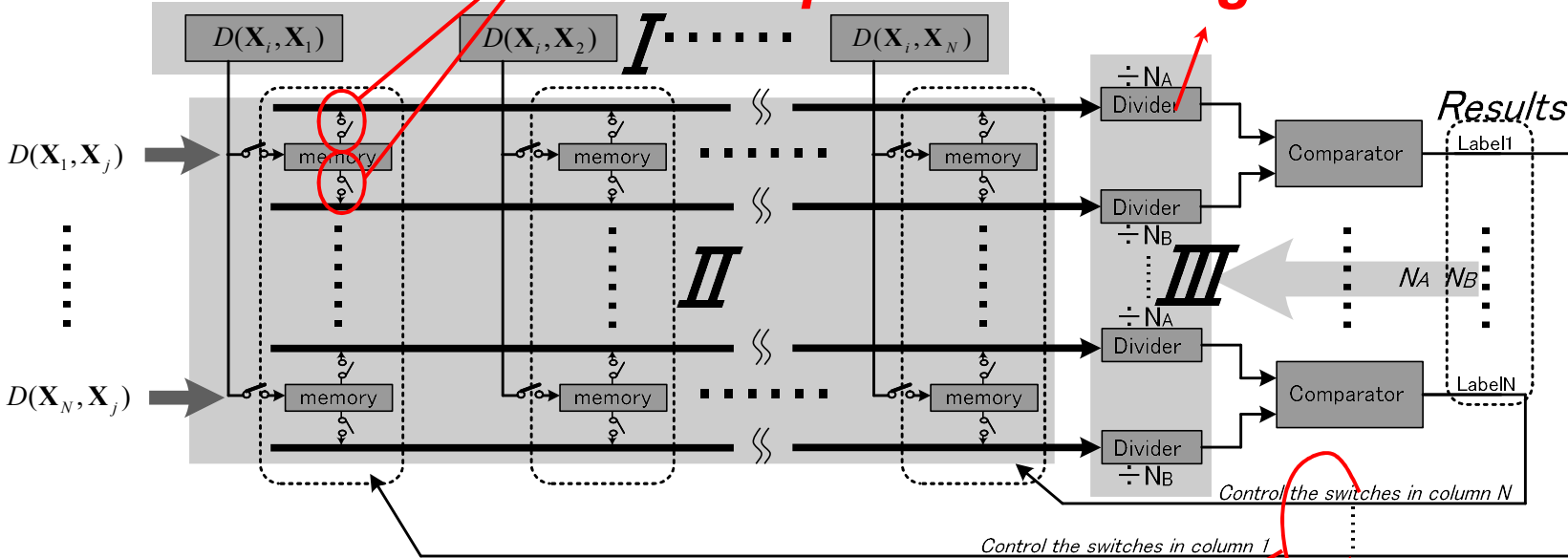
➤ **Our basic idea**

Learning based on the calculations among **scalars**
Possible to implement in fully-parallel

Fully parallel KQC processor

➤ Hardware implementation (two clusters)

Switches reflect the cluster label of this pattern
Compute the average distance

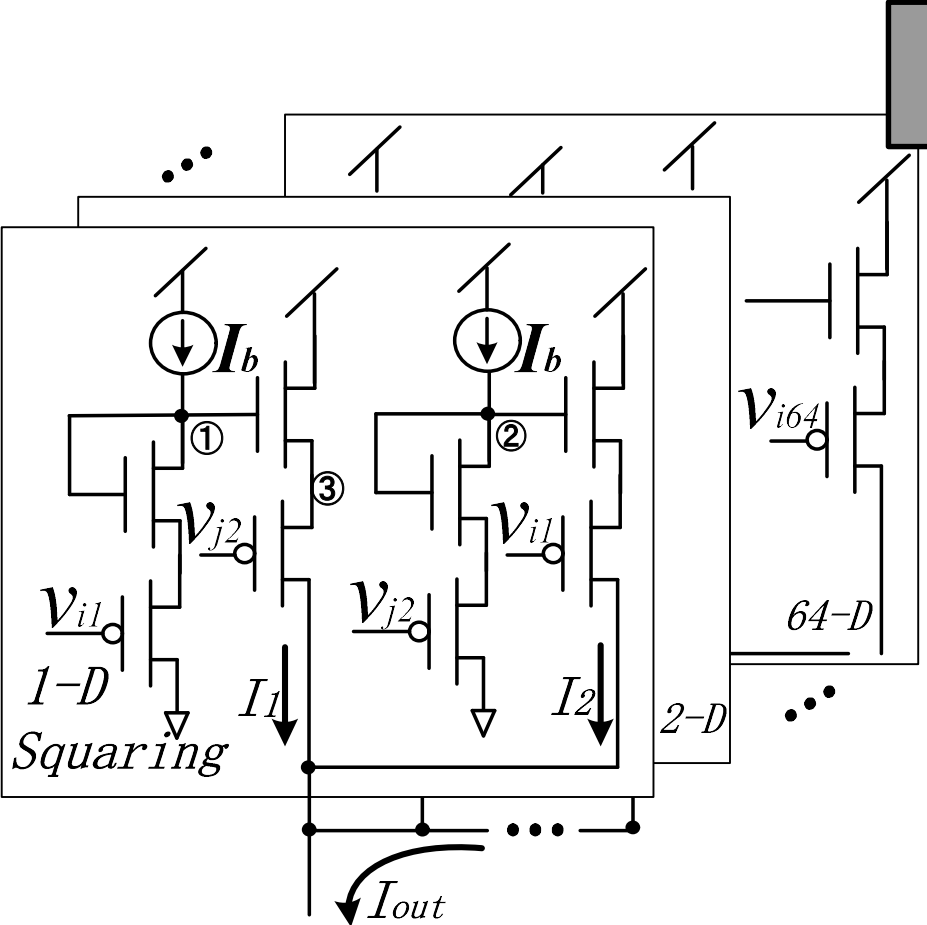


Control the switches

Fully-parallel, free and real-time feedback, self-converge

Fully parallel KQC processor

➤ Euclidean distance



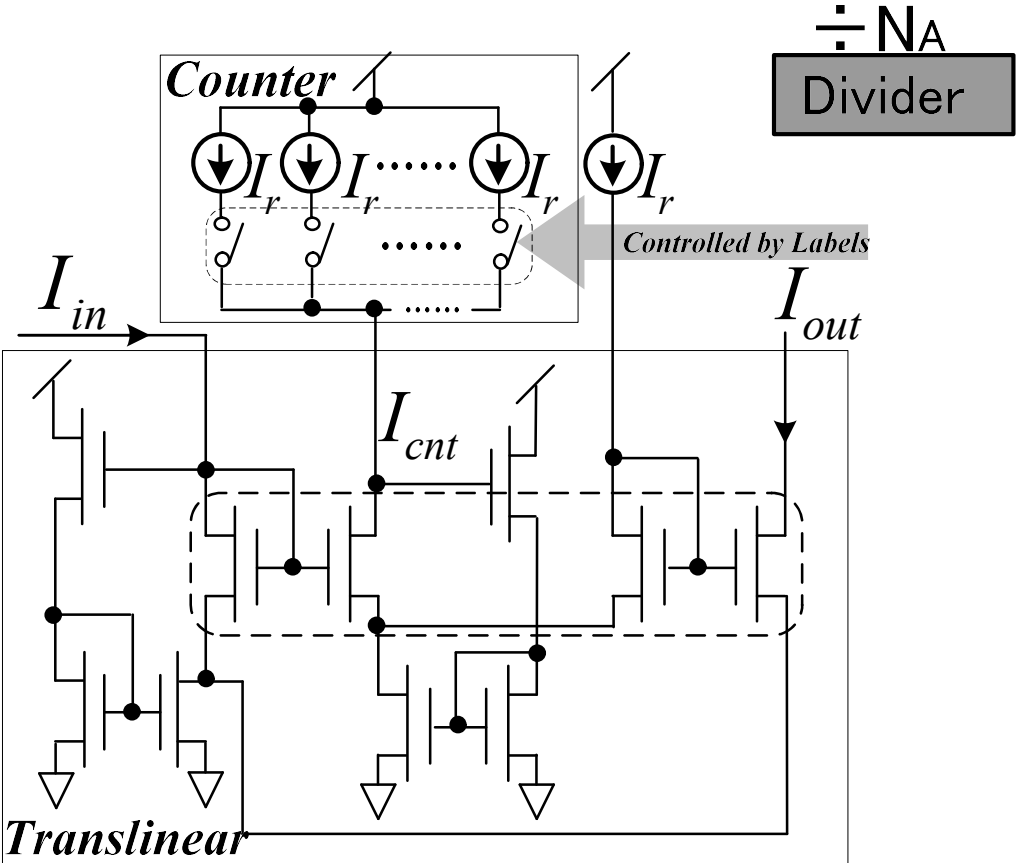
$$D(\mathbf{X}_i, \mathbf{X}_j)$$

$$I_{out} \approx \alpha \sum_{k=1}^{64} (v_{ik} - v_{jk})^2$$

$$\alpha = \frac{K_n K_p}{(\sqrt{K_n} + \sqrt{K_p})^2}$$

Fully parallel KQC processor

➤ Average



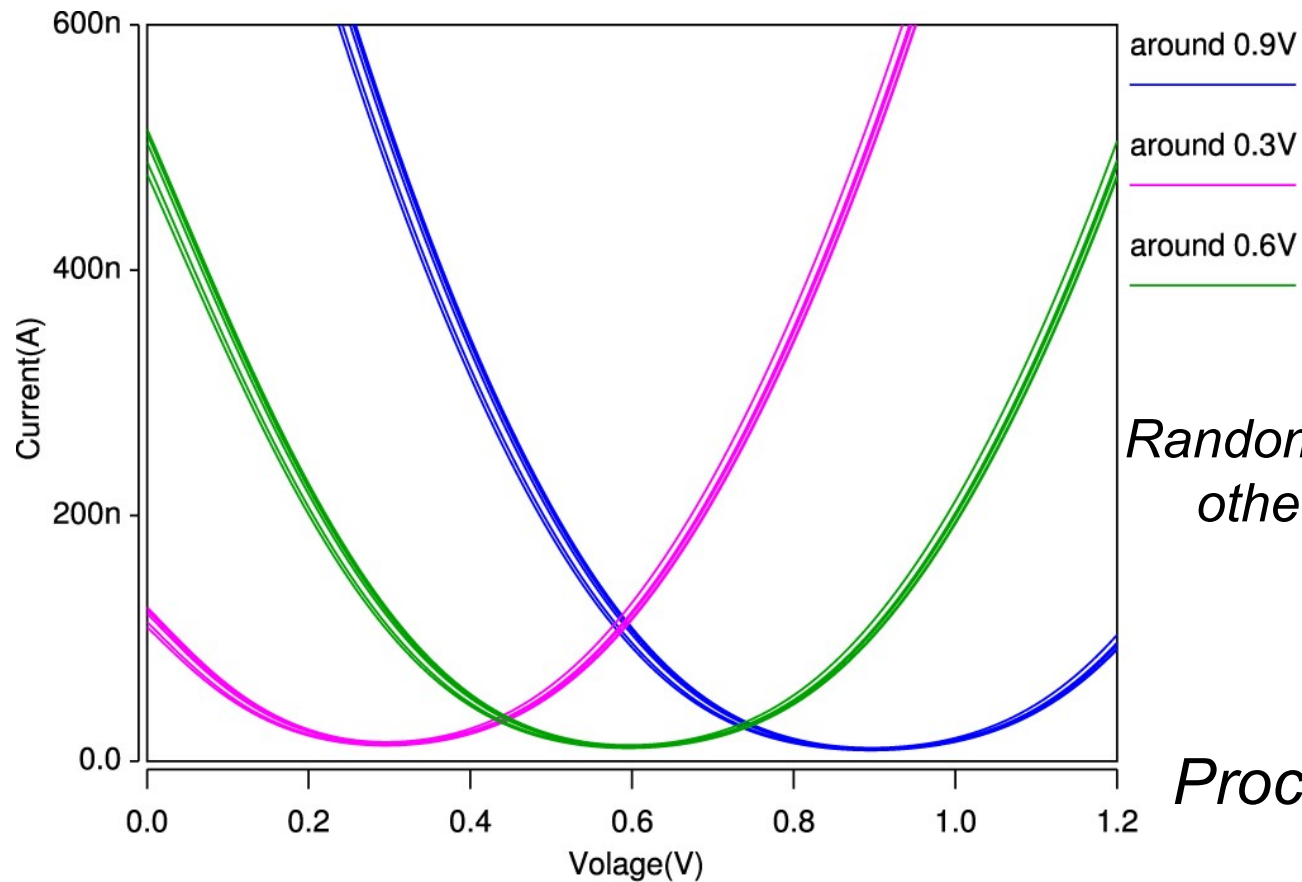
$$I_{out_A} \approx \frac{I_{in}}{N_A}$$

or

$$I_{out_B} \approx \frac{I_{in}}{N_B}$$

Fully parallel KQC processor

➤ Euclidean distance



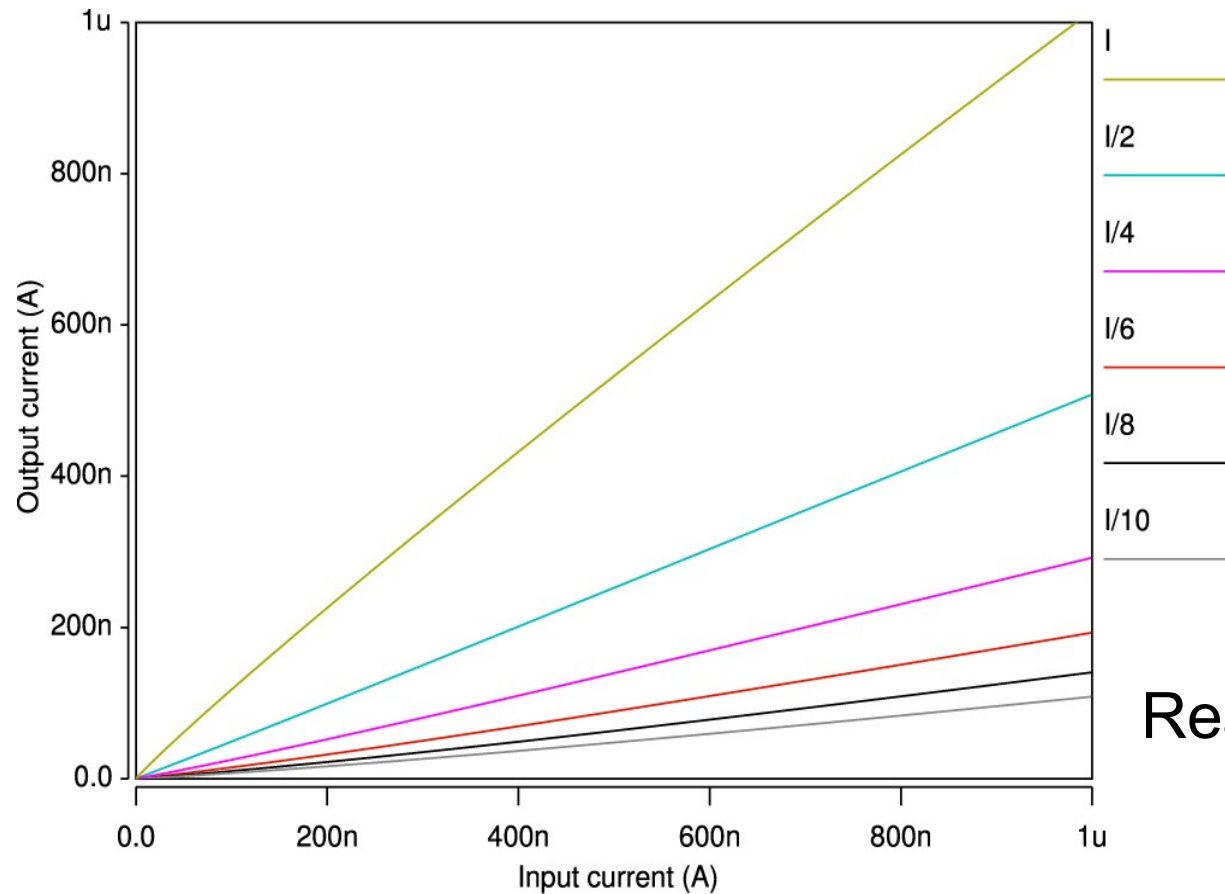
Simulation

*Randomly select a dimension,
others are constant*

Process variation: 5%

Fully parallel KQC processor

➤ Translinear (divider)

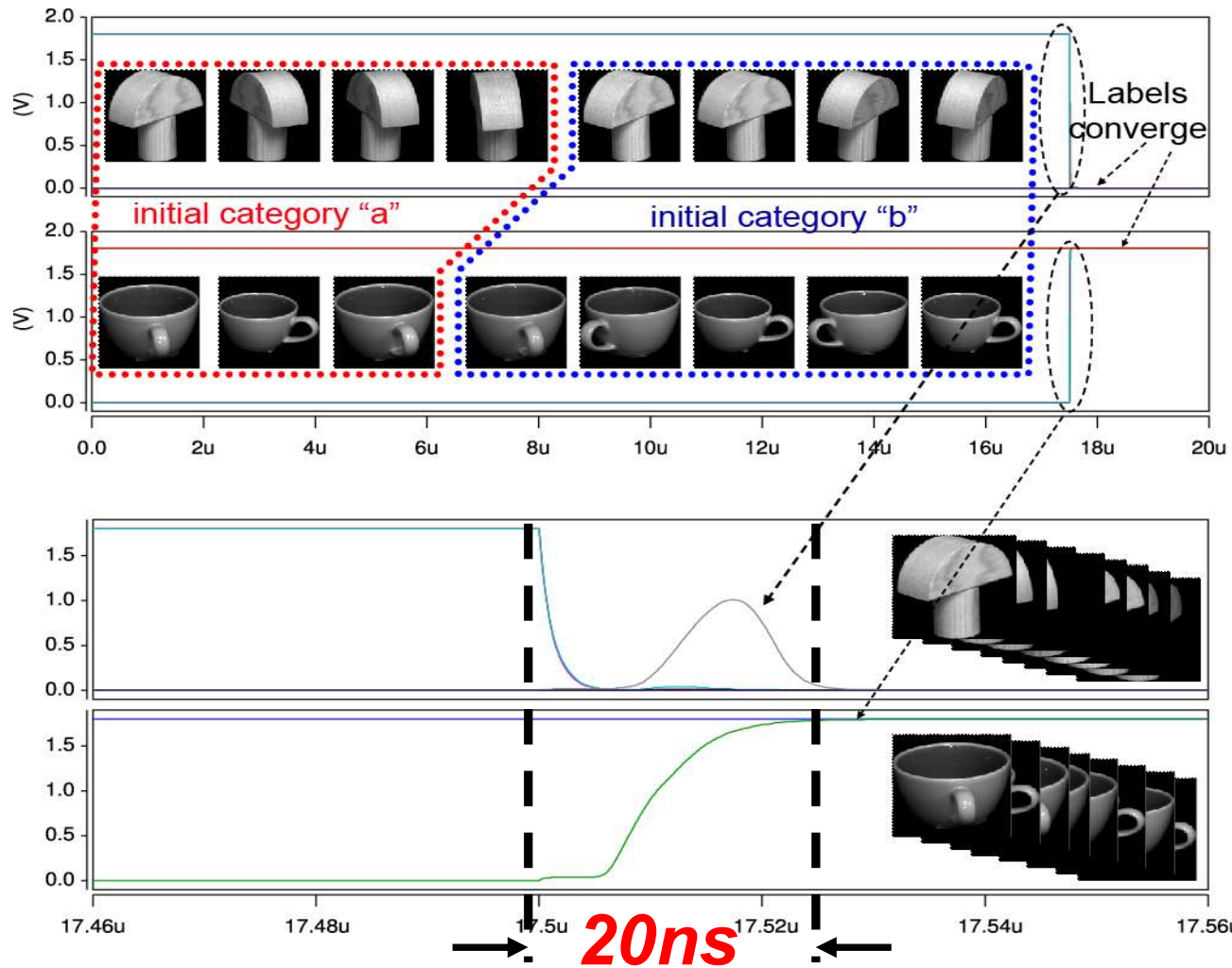


Simulation

Real-time computation

Fully parallel KQC processor

➤ Image clustering



Fully parallel KQC processor

➤ Performance

Comparisons

	[3]	[4]	This work
Implementation	FPGA & CPU	Digital	Analog
Number of devices	N/A	414K gates	20K Tran.s
Distance measurement	Manhattan	Euclidean	Euclidean
Number of dimensions	2	1 ~ 8	1 ~ 64
Number of iterations	25	16	self-converging
Speed (vectors/s)	$< 4.93 \times 10^6$	1.38×10^6	10×10^6
No. of samples	2905	76.8×10^3	16

[3] H. M. Hussain et al, *NASA/ESA Conf. Adaptive Hardware and Systems*, 2011, pp. 246-255.

[4] T.-W. Chen and S.-Y. Chien, *IEEE Trans. VLSI Syst.*, vol. 11, no. 8, pp. 1336-1345 (2011).

K-Quasi-Centers clustering

Summary

Proposed architecture can be applied in pattern clustering problems, with improved performances

Problems

Limited hardware resource

V.S.

Huge database

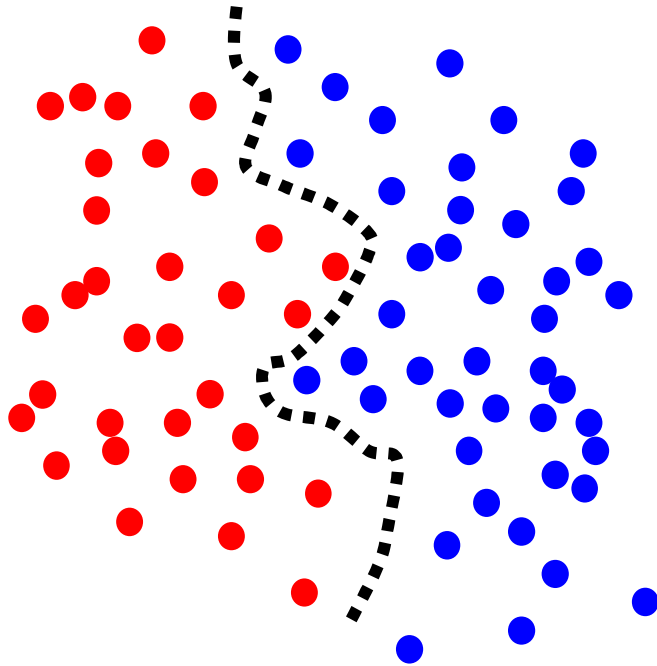
Unpredictable database

Outline

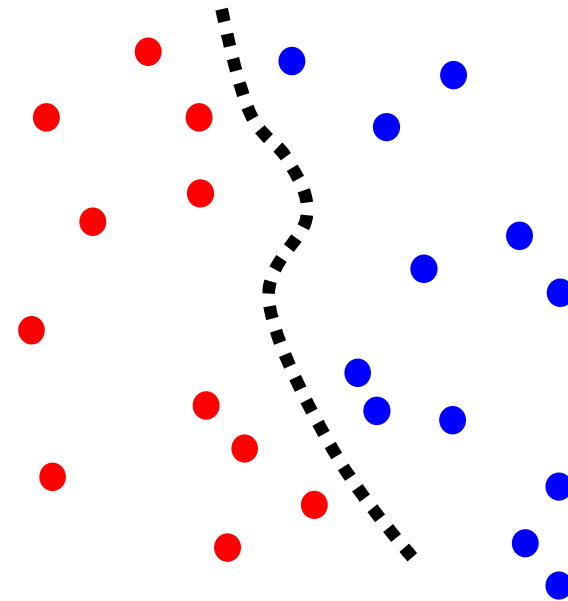
Analog implementations of them:

- Support Vector Machine
- K-Quasi-Centers clustering
- **On-line learning strategies**
- Data domain description
- Intel Project

On-line learning



Great performance
But difficult to train

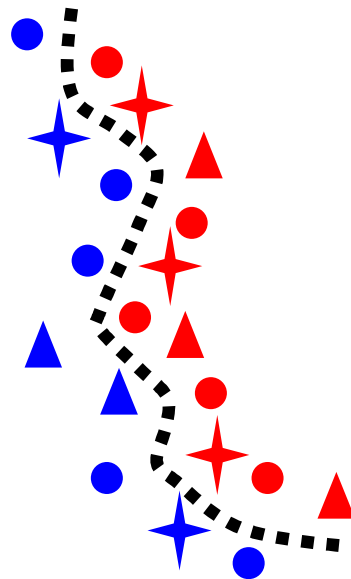


Easy to train
But performance is poor

Hardware resource is limited

On-line learning

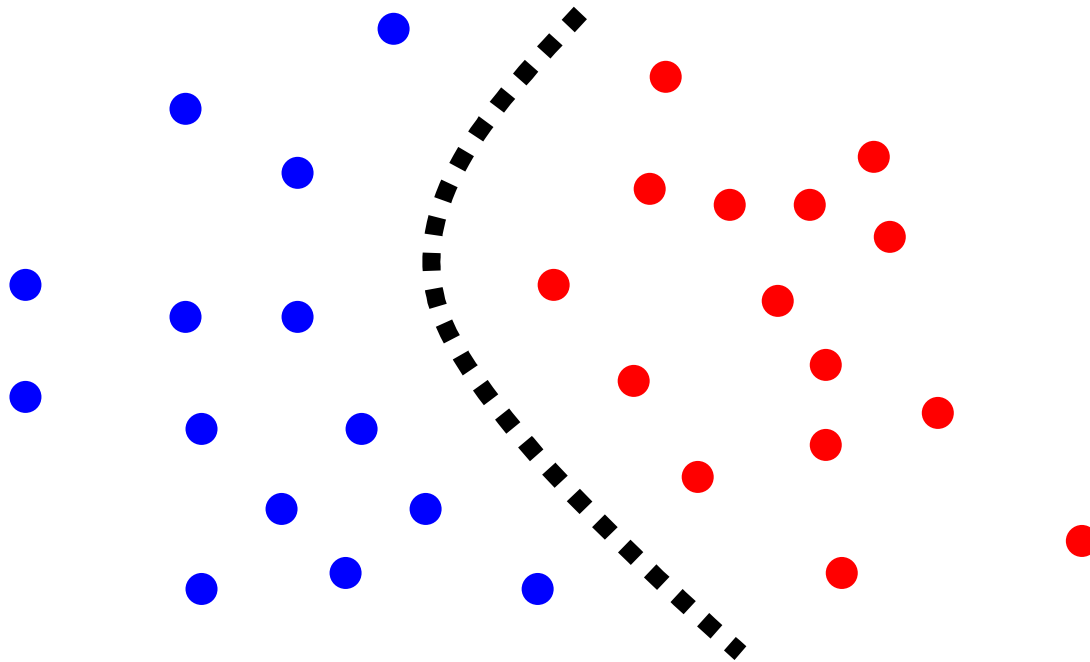
We wish:



On-line learning strategy is developed for this purpose

On-line learning

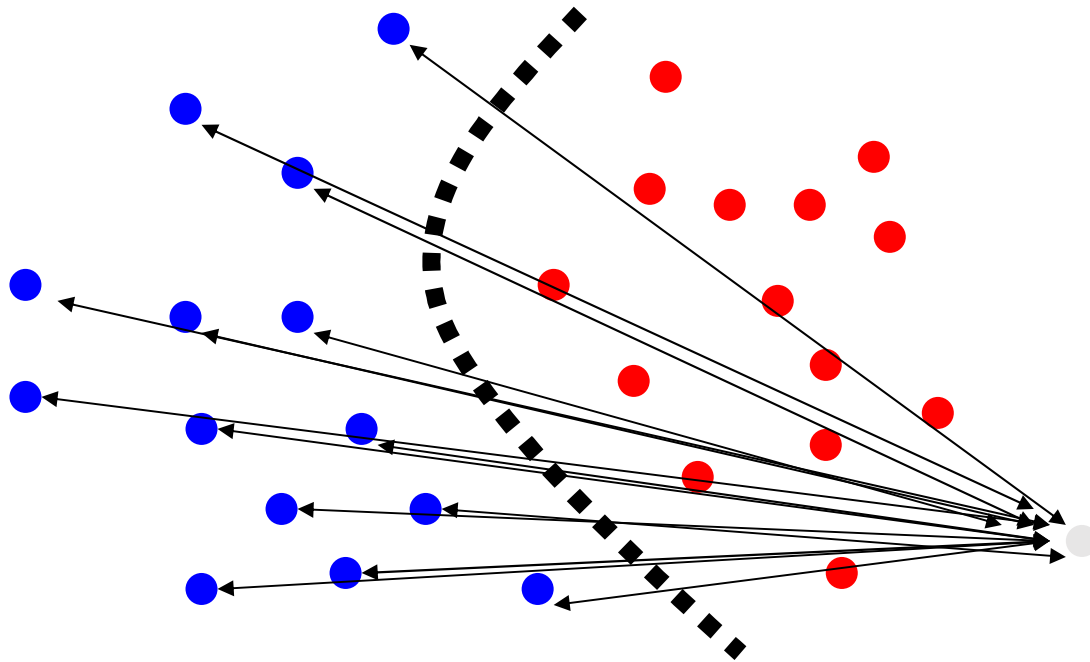
➤ Our proposal



Half-supervised

On-line learning

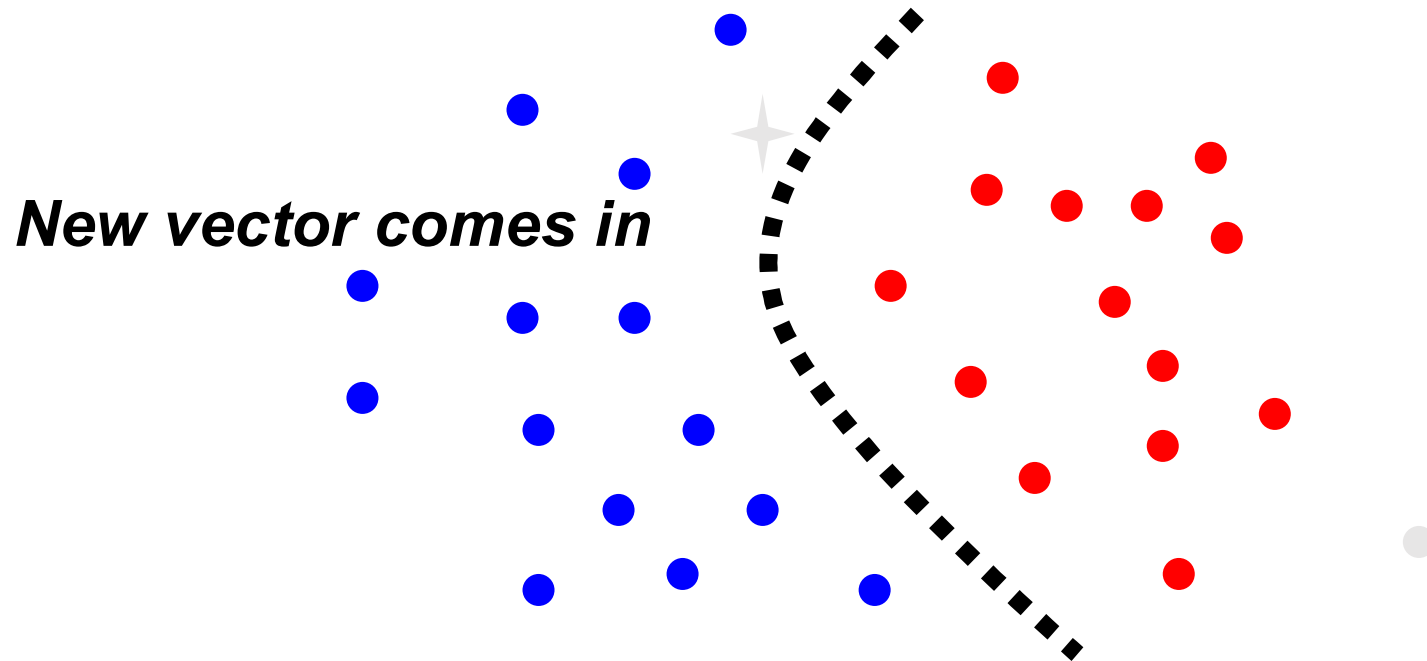
➤ Our proposal



Fortunately, it is possible only in fully-parallel system

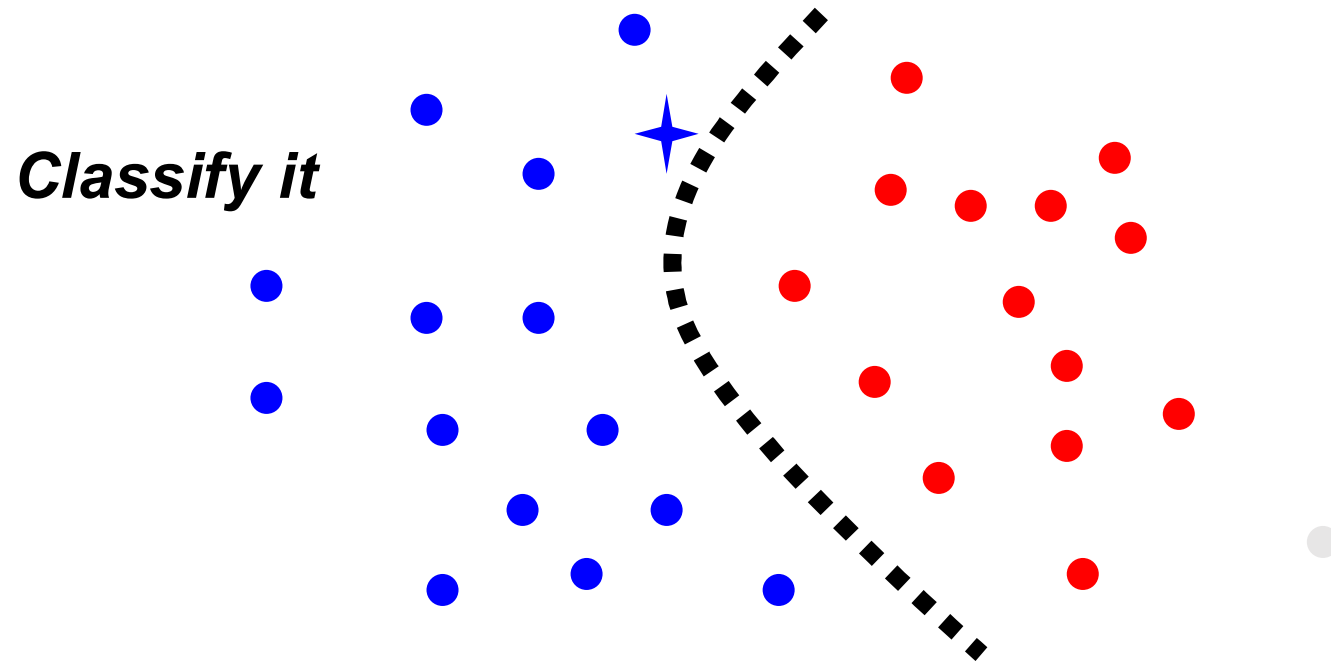
On-line learning

➤ Our proposal



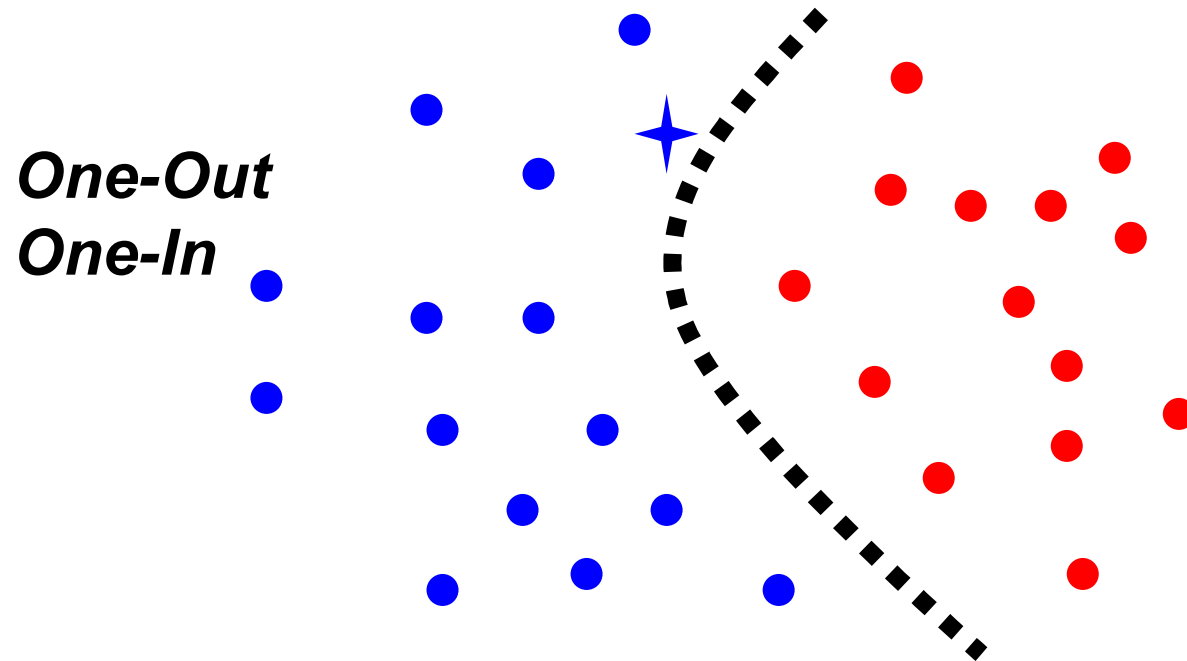
On-line learning

➤ Our proposal



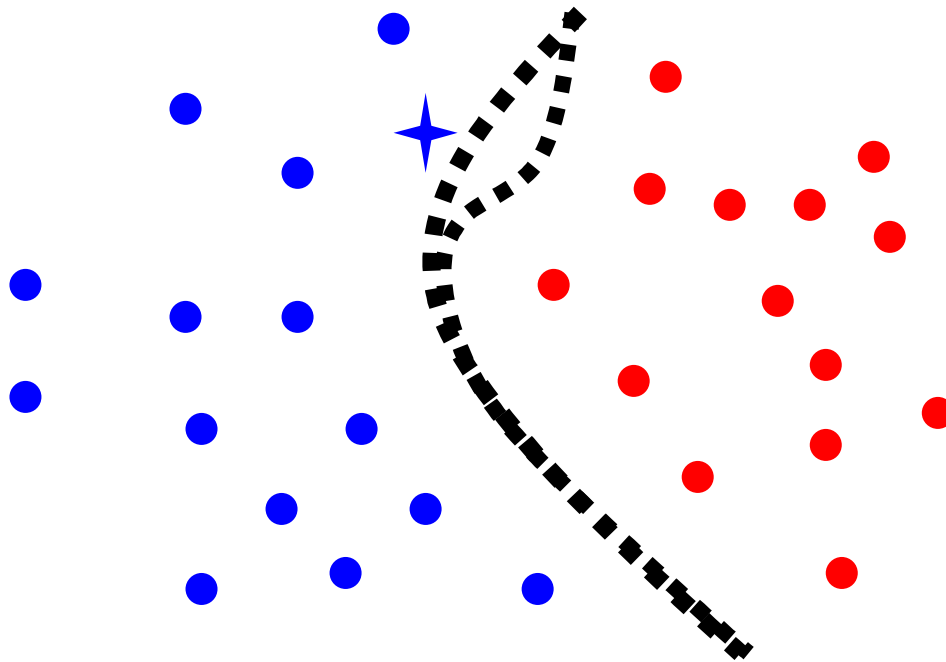
On-line learning

➤ Our proposal



On-line learning

➤ Our proposal

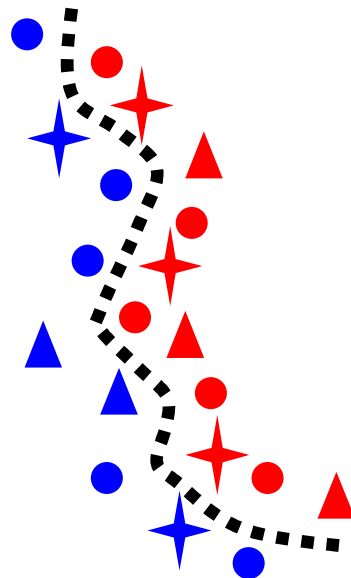


Learning again

On-line learning

➤ Our proposal

Finally

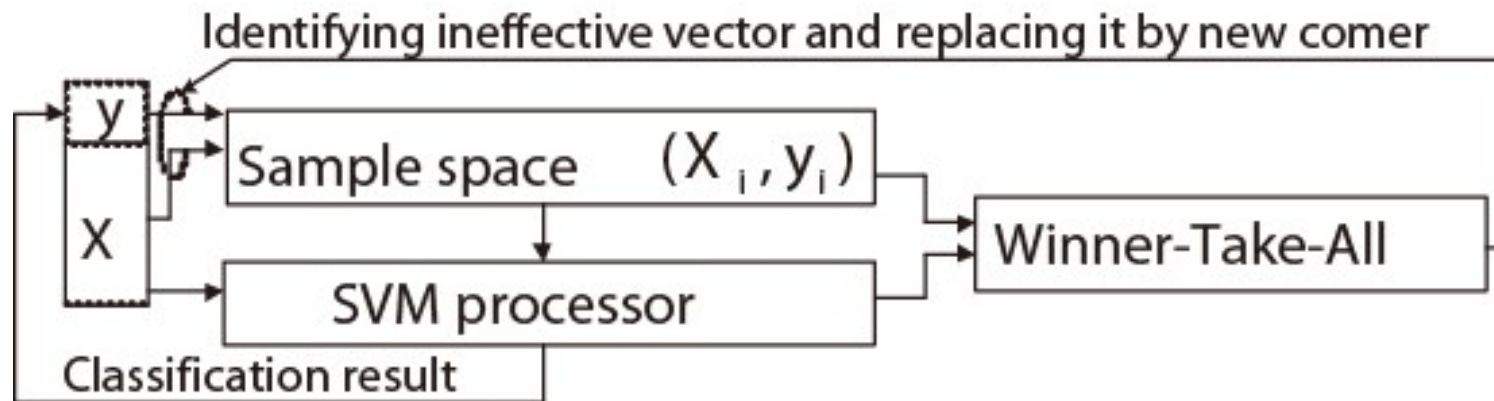


This strategy is suitable for fully parallel hardware implementation

On-line learning

Hardware implementations

On-line SVM



On-line learning

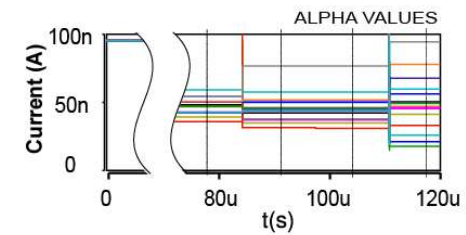
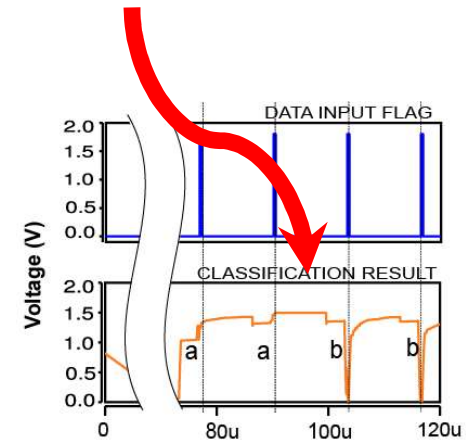
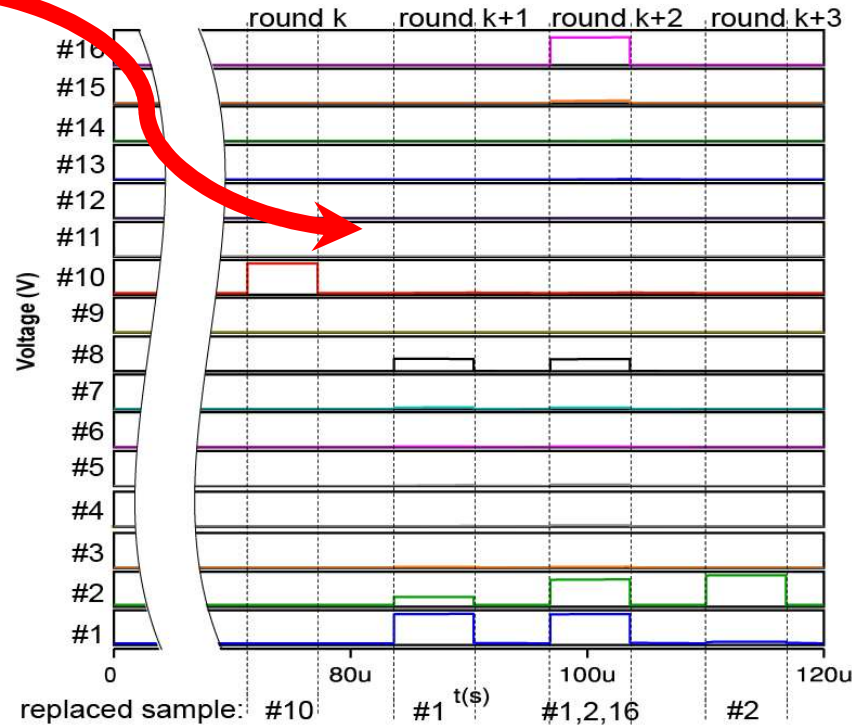
Hardware implementations

On-line SVM

Which one is useless?

New comer is ...?

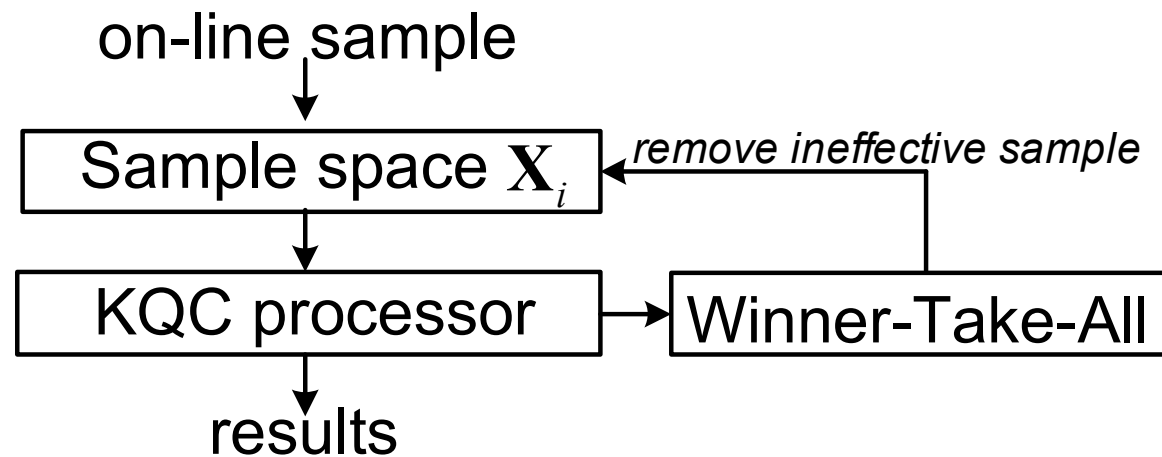
Simulation



On-line learning

Hardware implementations

On-line KQC learning

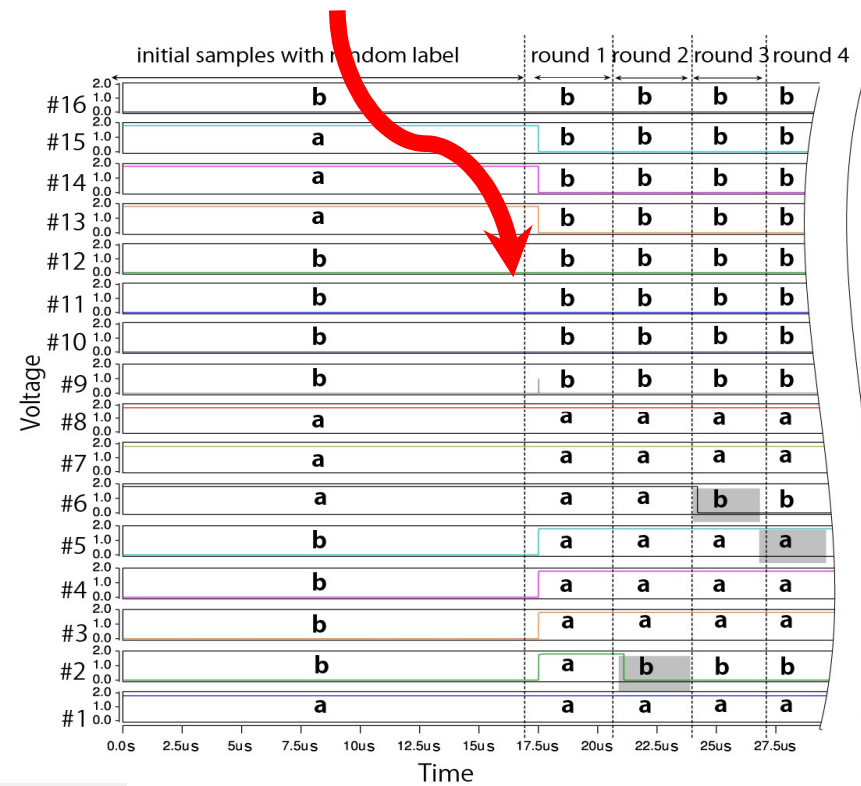
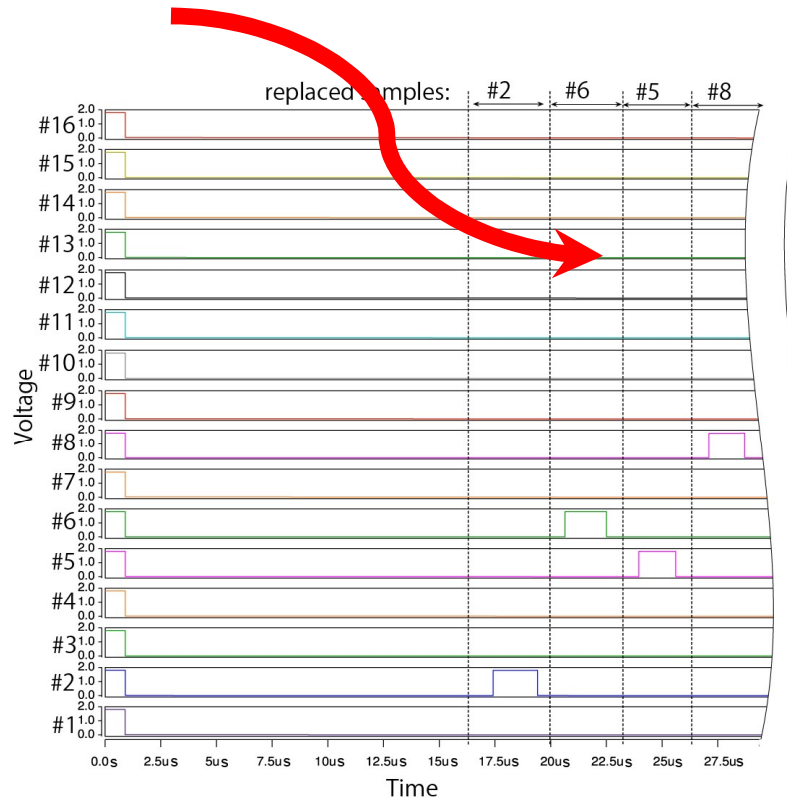


On-line learning

On-line K-means

Which one is useless?

How to cluster them?



Simulation

Application example

Is this kind of hardware feasible to be used in the real-world applications?

An object tracking system was built by our group-member Mr. Zhao, employing an SVM chip fabricated in this work.

Application example

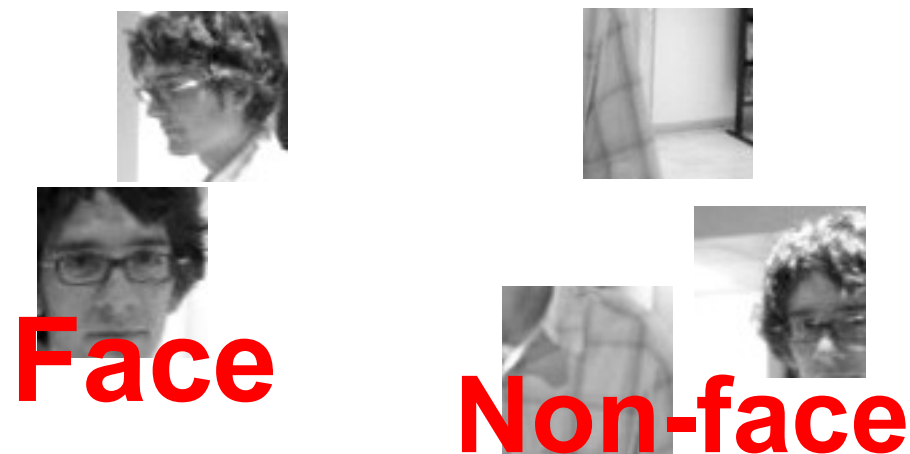
SVM in tracking

*Target:
find face in video*



*Framework of system was
built by Mr. Zhao*

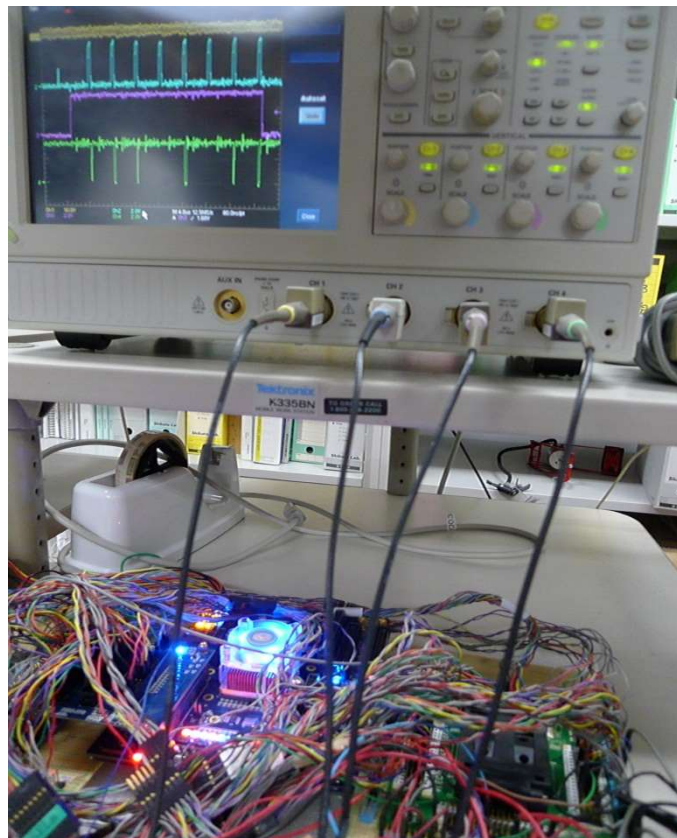
*SVM:
distinguish face and background*



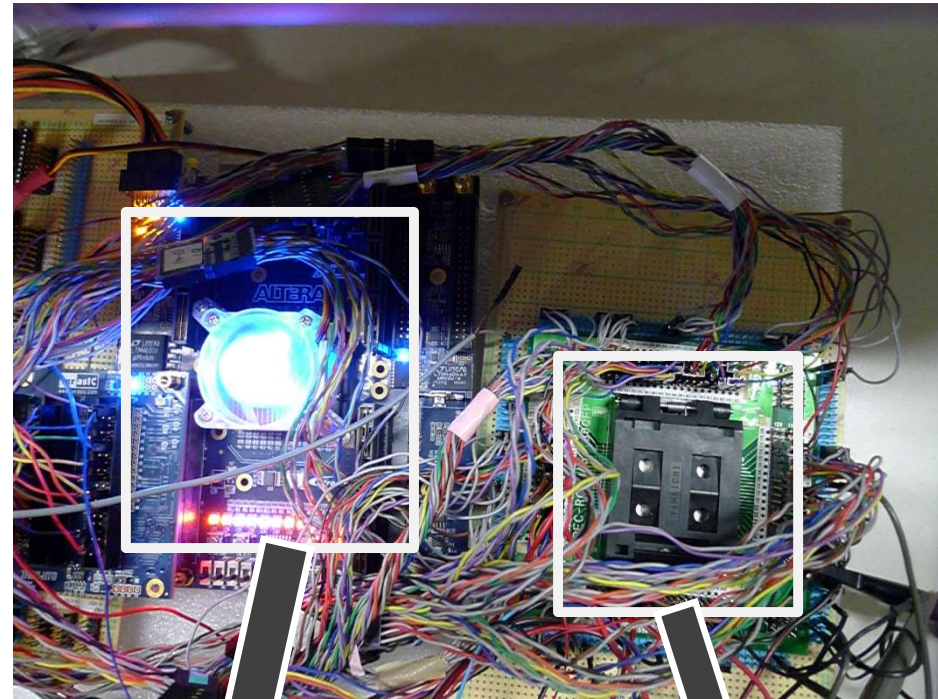
Analog SVM chip was employed

Application example

SVM in tracking



Framework of system was built by Mr. Zhao



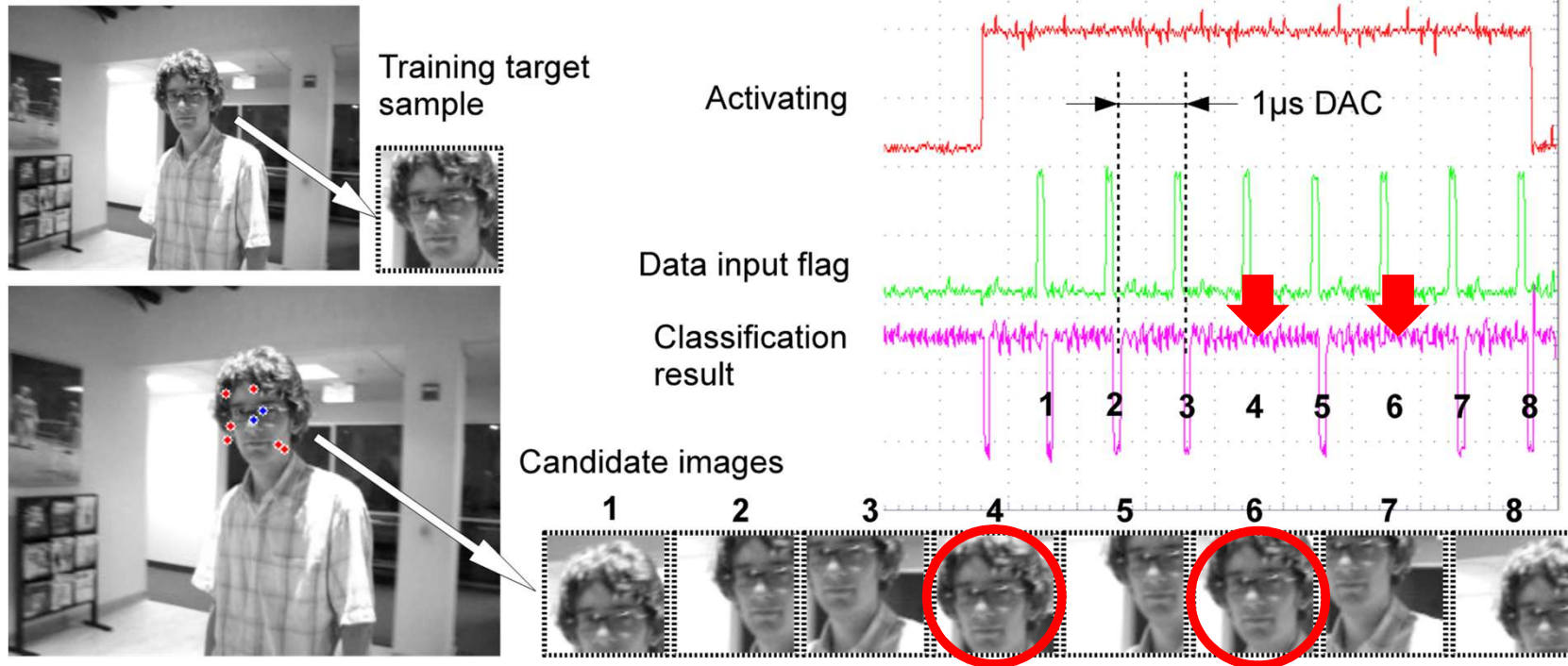
FPGA: Tracking Framework

Analog SVM chip

Analog SVM chip was employed

Application example

SVM in tracking



Object Tracking With On-Line Shape Learning



P. Zhao, R. Zhang, and T. Shibata, "Real-time Object Tracking Algorithm Employing On-Line Support Vector Machine and Multiple Candidate Regeneration," ICAISC, 2012, Poland.

On-line learning

Summary

- ✓ *Proposed on-line learning strategy, which is on the basis of fully parallel architecture, helps to improve hardware flexibility and efficiency.*
- ✓ *Proposed hardware is feasible to use in real-world applications.*

R. Zhang and T. Shibata, LNCS, 2012.

R. Zhang and T. Shibata, *J. Analog Integrated Circuits and Signal Processing* (Springer), 2012.

P. Zhao, R. Zhang and T. Shibata, LNCS, 2012.

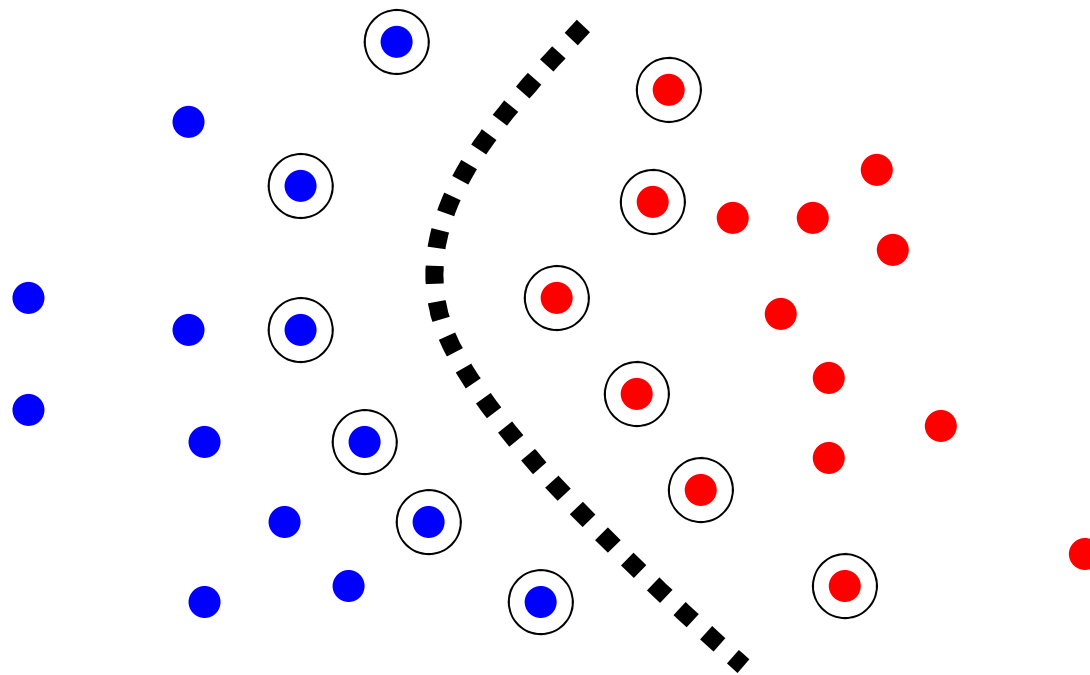
Outline

Analog implementations of them:

- Support Vector Machine
- K-Quasi-Centers clustering
- On-line learning strategies
- **Data domain description**
- Discussion on scalability

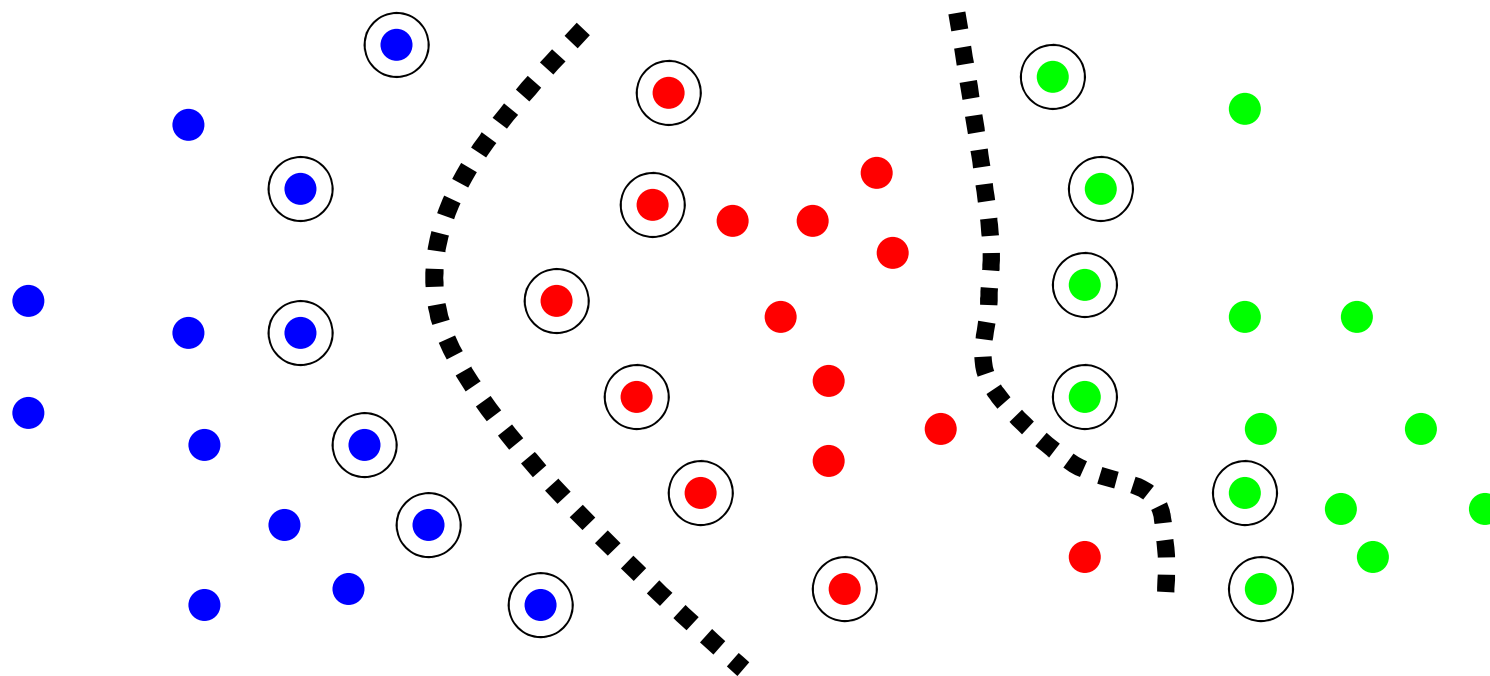
Data domain description

Standard SVM can do this well:



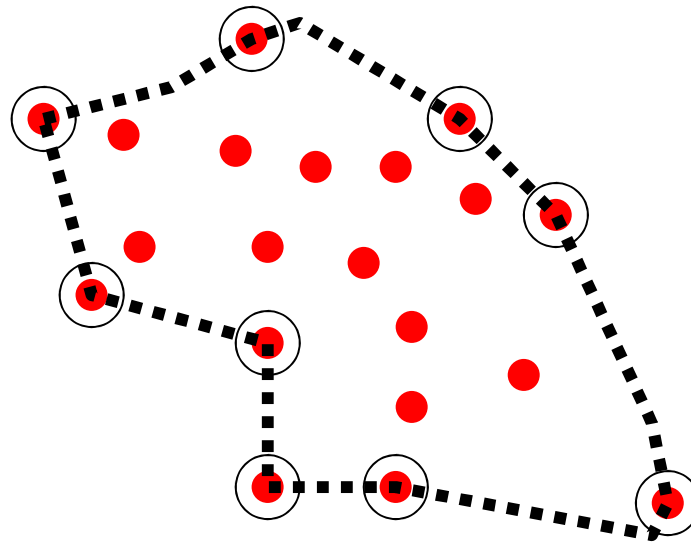
Data domain description

Standard SVM can do this somehow:



Data domain description

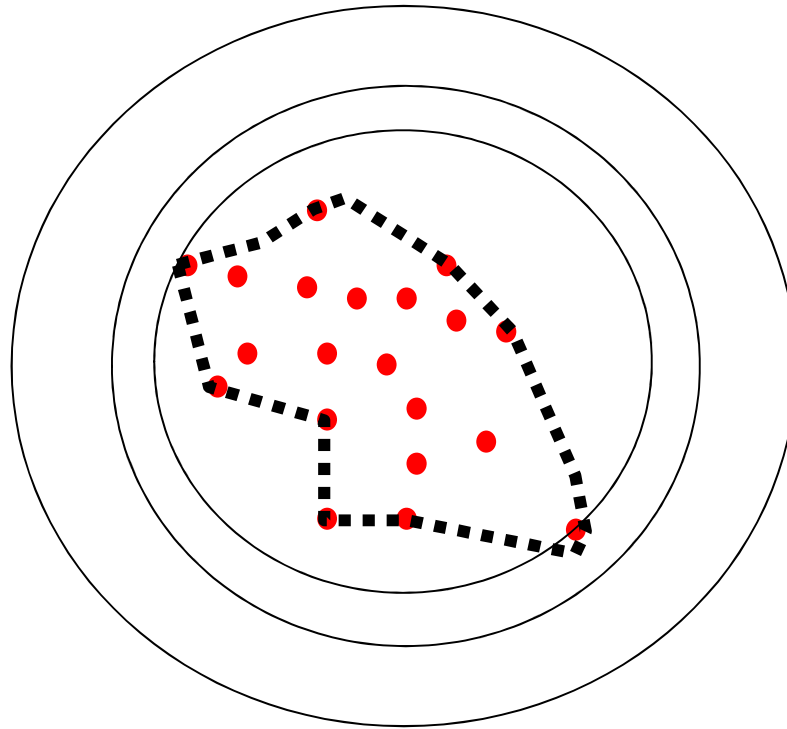
How about this?



Data domain description

Support vector domain description (SVDD) was developed

But, expensive to train it



Find a sufficiently compact and fit boundary, including almost all samples

Data domain description

Derivations in appendix 2

Algorithm:

To make: $(\mathbb{X}_i - \mathbf{a})^T (\mathbb{X}_i - \mathbf{a}) \leq R^2 + \xi_i$, **With minimum R**

Becomes: $\min L = 1 - \sum_i \alpha_i^2 - \sum_{i \neq j} \alpha_i \alpha_j K(\mathbb{X}_i, \mathbb{X}_j)$

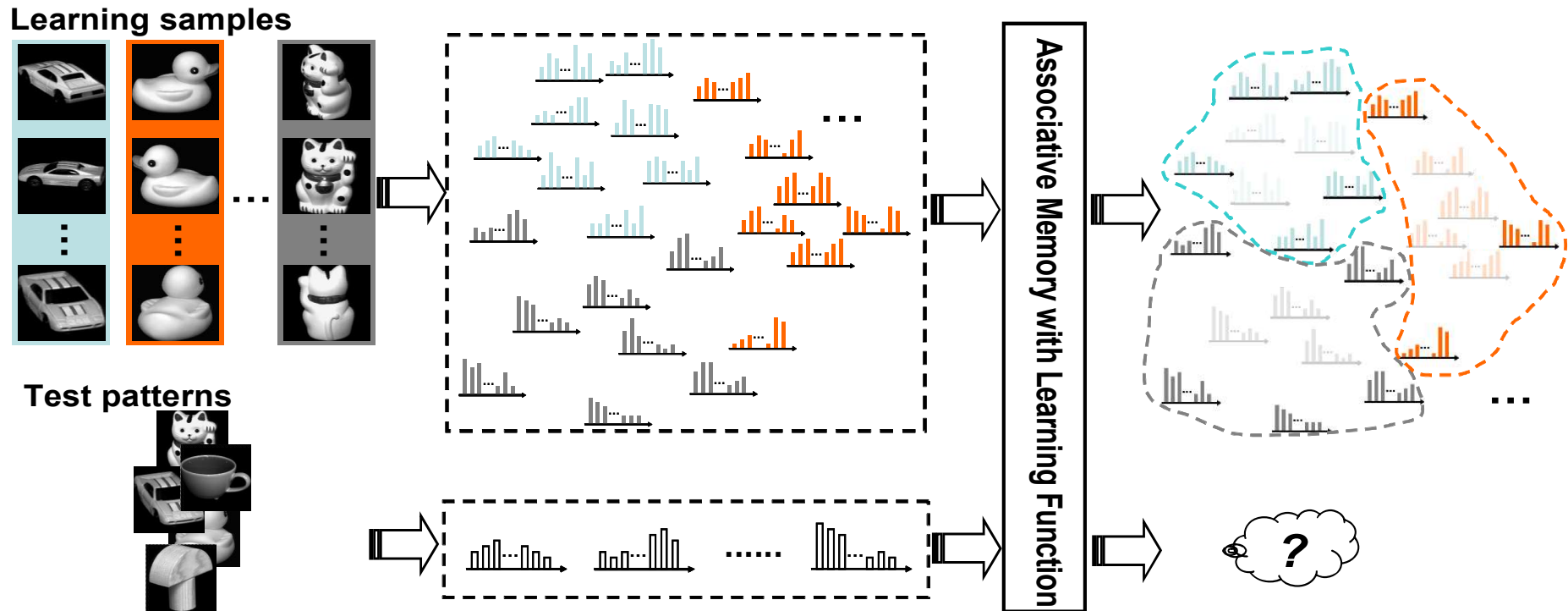
with: $\sum_i \alpha_i = 1$



$$\begin{cases} \alpha_i \leftarrow \frac{1}{2} (\lambda - \sum_{j \neq i} \alpha_j K_{ij}) \\ \lambda \leftarrow \frac{1}{N} (1 + \sum_i \sum_j \alpha_j K(\mathbb{X}_i, \mathbb{X}_j)) \end{cases}$$

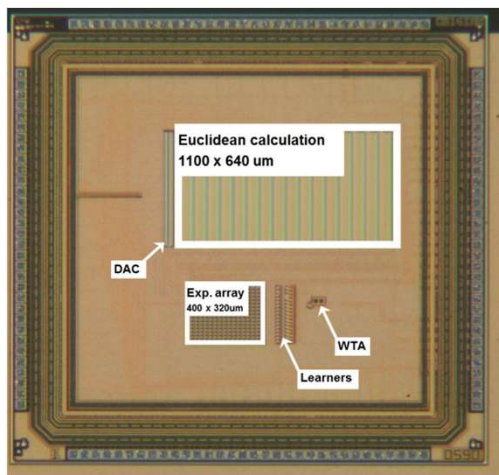
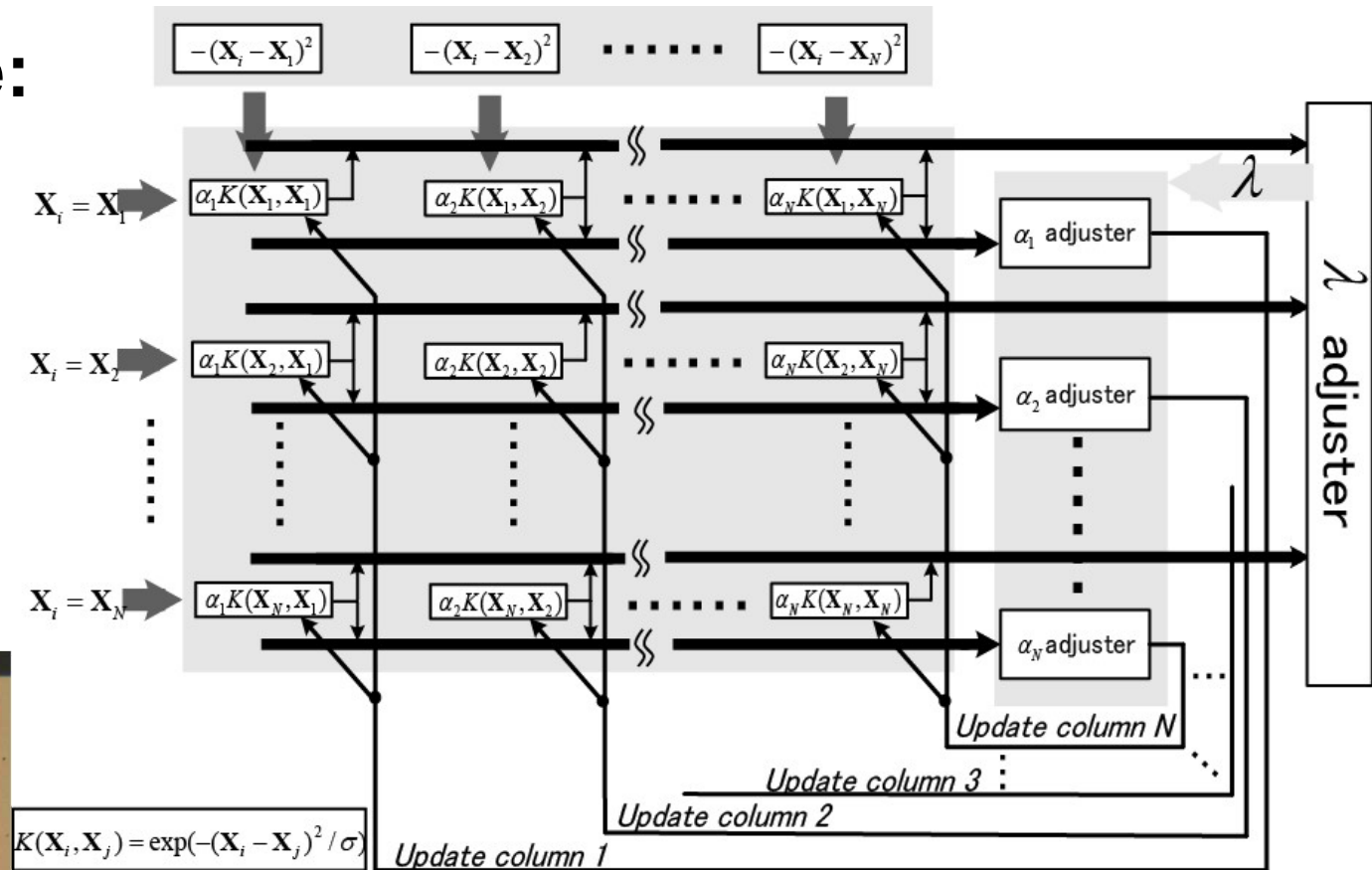
Data domain description

In the real-world applications:



Data domain description

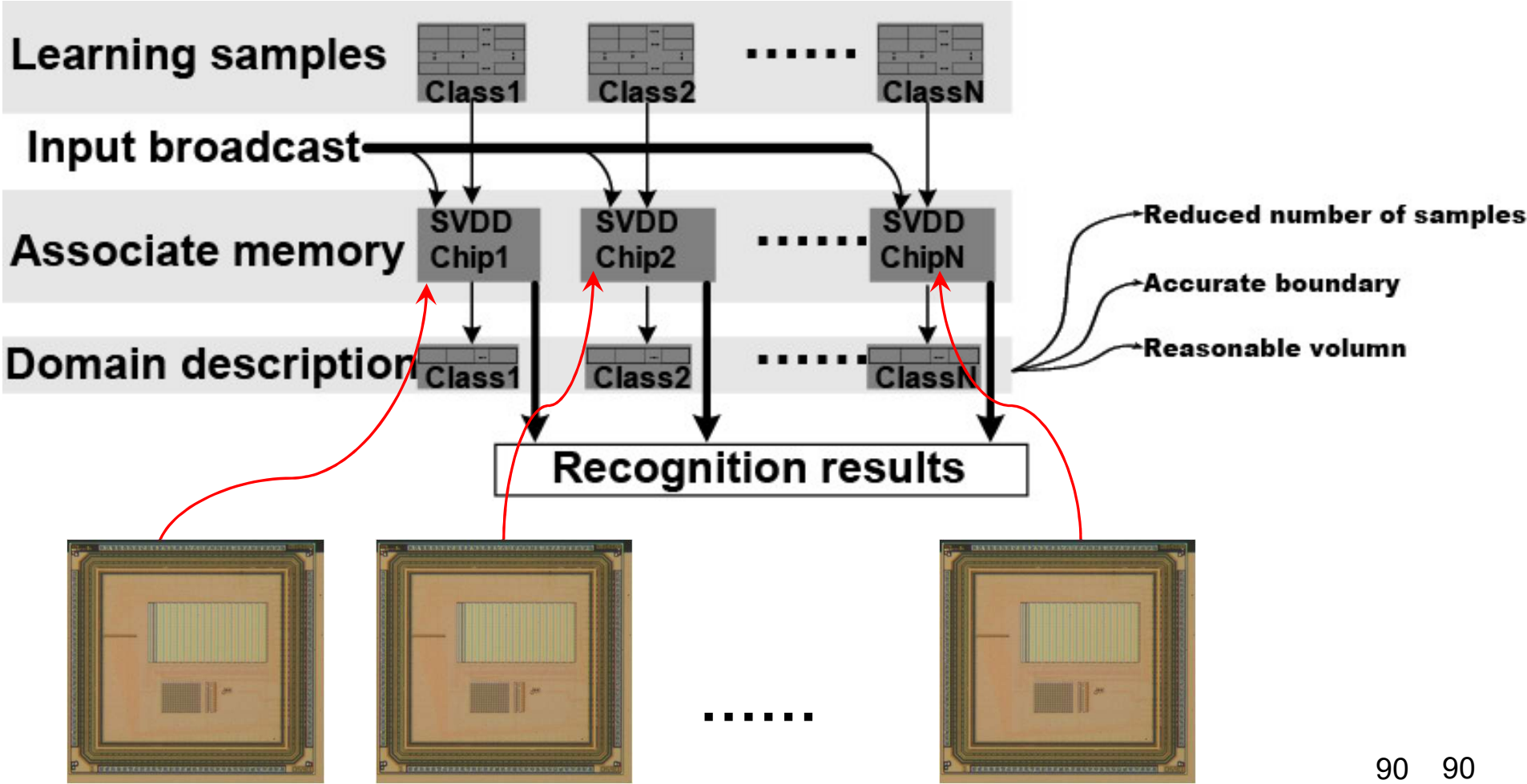
Architecture:



$$\begin{cases} \alpha_i \leftarrow \frac{1}{2} (\lambda - \sum_{j \neq i} \alpha_j K_{ij}) \\ \lambda \leftarrow \frac{1}{N} (1 + \sum_i \sum_j \alpha_j K(X_i, X_j)) \end{cases}$$

Data domain description

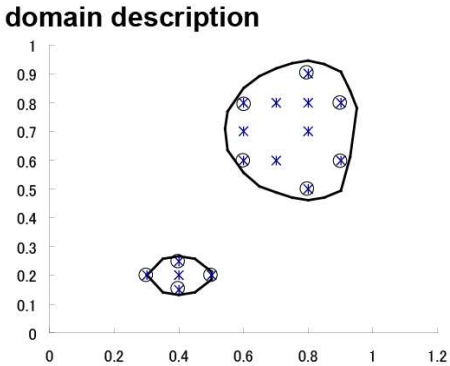
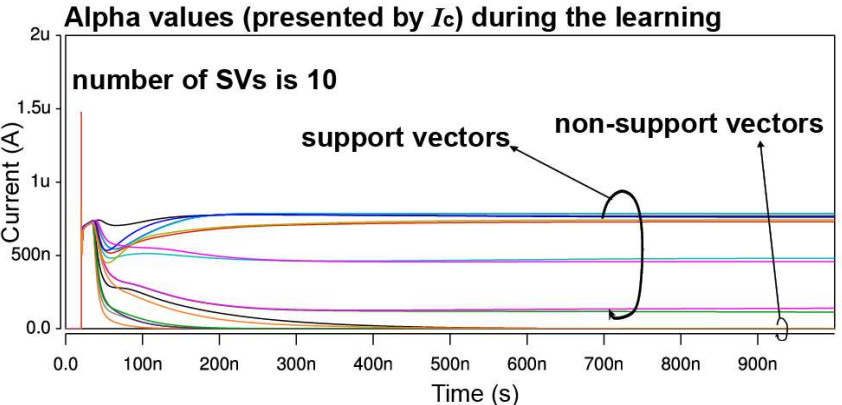
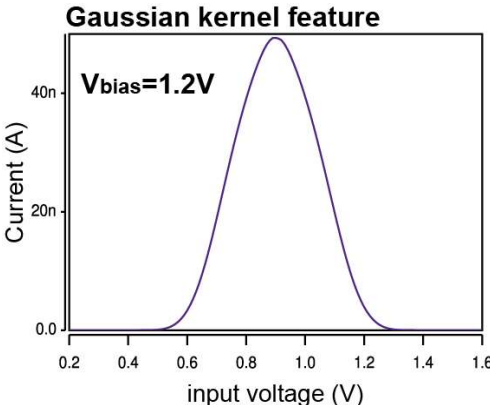
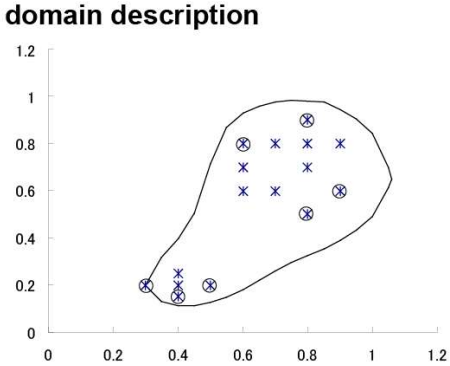
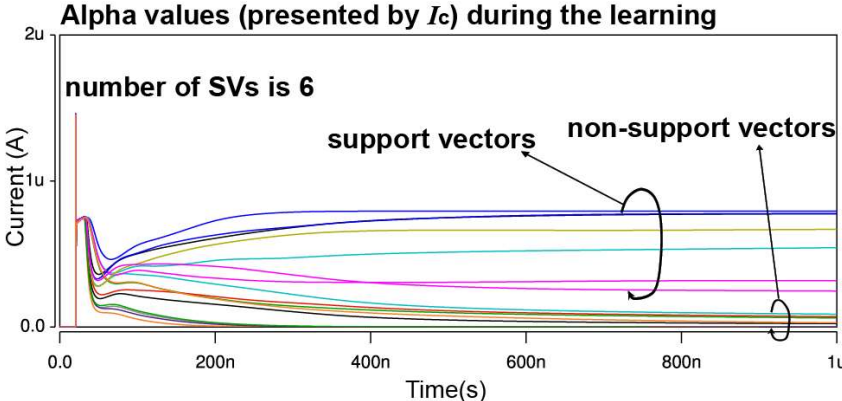
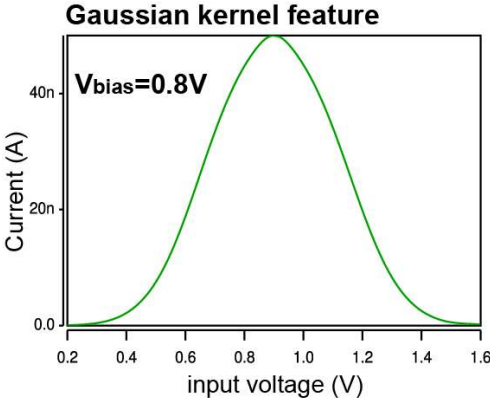
In the real-world applications:



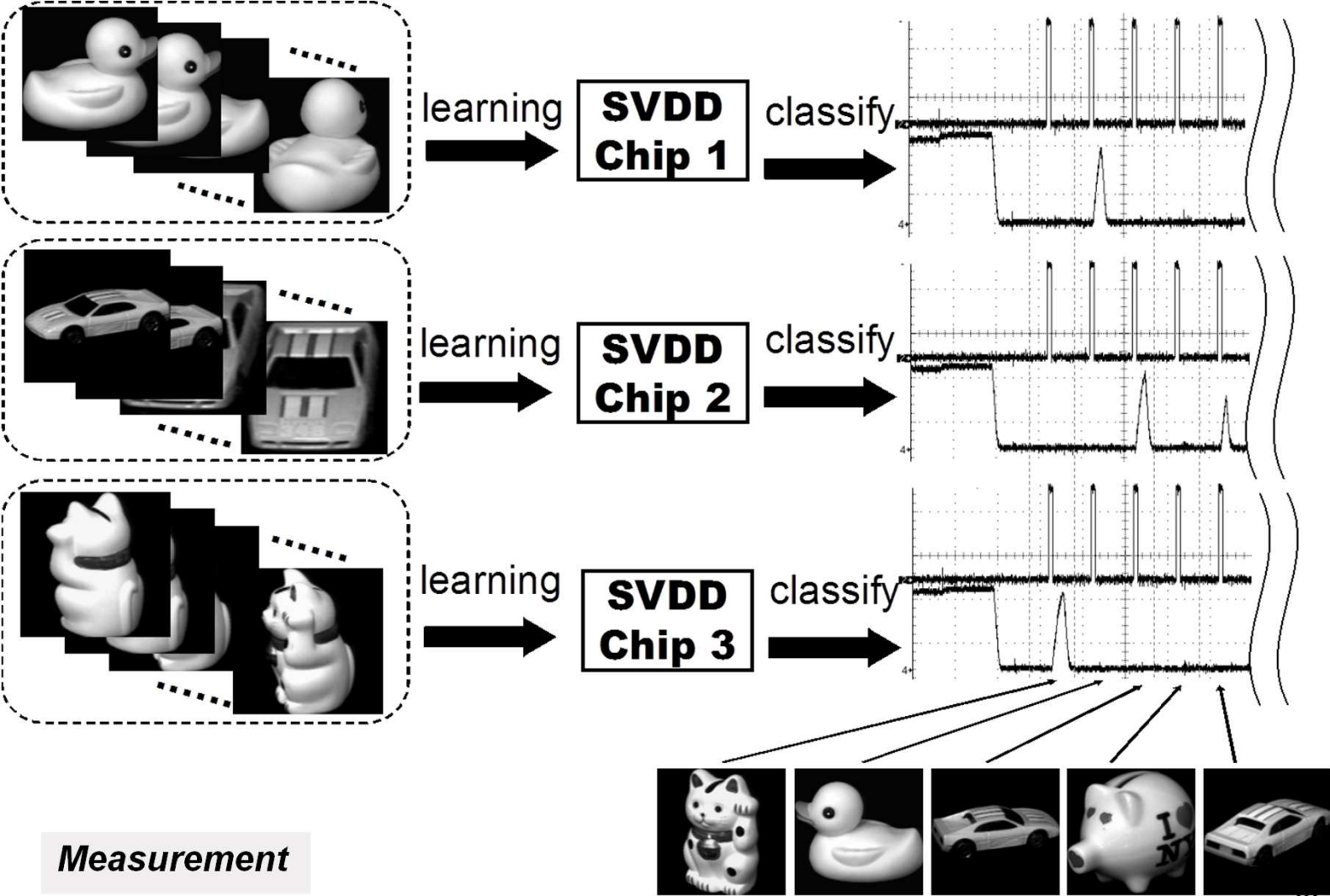
Data domain description

Using the fully parallel array:

Simulation



Data domain description



Data domain description

Summary

SVDD is more similar to human perception, it can be implemented by the proposed architecture with mathematical tricks.

Last dance

Gap makes people hop

End



Thank you very much.